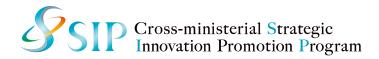
Infrastructure Maintenance, Renovation and Management





Introduction; The R&D Project of Infrastructure

Greeting

For Safe and Secure Infrastructure Systems

The Cross-Ministerial Strategic Innovation Promotion Program (SIP), in which the Council for Science, Technology and Innovation (CSTI) plays the role of playmaker, has been established to realize scientific technology innovations. As a cross-ministerial and cross-field program, SIP will drive forward with the focus ranging from basic research to commercialization/industrialization. "Infrastructure maintenance, renovation and management" (hereinafter referred to as "SIP infrastructure") is one of the issues currently under the focus of the programs.

Civil infrastructures, such as roads, railways, harbors and airports, support our everyday life and social economic activities. Many of them, however, were built during the high economic growth period. As they get older, the increase in maintenance and repair expenditures, along with the possibility of a serious accident occurring during the service, become serious social issues. This program aims at preventing accidents and reducing the burden of maintenance by constructing a systematic infrastructure management that utilizes the most advanced information and robotics technologies.

Unlike mass-produced products, such as vehicles and laptop computers, infrastructures are single products that are designed, constructed, and manufactured individually. Initial conditions of infrastructures vary depending on the time and condition they were built . As a result, in addition to the difference in usage environment, the speed of infrastructure deterioration also varies. Some infrastructures that have been used for several tens of years may pose a higher risk of accident due to damage. To allow for an effective and efficient preventive maintenance management of infrastructures and to establish a safe and secure

infrastructure system, it is therefore crucial to have technologies that can precisely diagnose and take appropriate measures by closely examining large number of infrastructures individually on-site. It is also essential to minimize the hazards and risks associated with manual handling in the workplace. For infrastructure management run by local governments, cost reduction is also a particularly important viewpoint. Currently, infrastructures are being constructed across Asia; however, maintenance has already become a big issue. "SIP infrastructure" aims at introducing new exciting advanced technologies into the range of infrastructure management technologies. Specific examples include the following: support from or replacement with robots for infrastructure inspection; on-site damage detection inside concrete members; inspection of tunnels and bridges by mobile sensors that do not require traffic control; technologies to aerially detect damage/deformation of river levees, dams, and harbors; highly accurate deterioration estimation technology for concrete; developing ultra-high durable repair materials: efficient infrastructure management technology using big data processing; and artificial intelligence.

Japan's infrastructure stock is estimated to be over 800 trillion yen. Infrastructures should function for several decades. Our responsibility to the future is to create an infrastructure information platform and to pass on the infrastructures that can be used safely with a minimum maintenance burden to the next generation. The objective of "SIP infrastructure" is to establish the system and we will work hard to achieve it.



PD (Program Director)

Yozo Fujino

Distinguished Professor, Institute of Advanced Sciences, Yokohama National University

Yozo Fujino graduated from Department of Civil Engineering, at the University of Tokyo in 1972. After completing his Master's degree (Civil Engineering) at the University of Tokyo, he received the Doctor of Philosophy from the University of Waterloo in 1976. He joined the Earthquake Research Institute at the University of Tokyo; the Institute of Structural Engineering at the University of Tsukuba; and Department of Civil Engineering at the University of Tokyo. In 1990, he was appointed as a professor of Department of Civil Engineering at the University of Tokyo. In 2014, he joined the Yokohama National University, and has served in his current position from October 2014. He is a Professor Emeritus of the University of Tokyo. His expertise includes structures, vibration control and monitoring of civil infrastructures with emphasis on bridges. He was awarded the Medal with Purple Ribbon of Honor from the Emperor of Japan in 2007, and the 2015 Hattori Hoko Award (The Hattori Hokokai Foundation), among others.

Outline

In Japan, amid the aging of infrastructures, emerging risk of a serious accident such as the Sasago tunnel accident in 2012, and the increase in maintenance and repair expenditures are topics of concern. Systematic infrastructure management utilizing new technologies is essential both for preventing accidents based on preventive maintenance system and minimizing life cycle cost of infrastructures under the conditions of the tight financial grounds and the decreasing number of skilled engineers. Particularly, technologies that utilize the world's most advanced ICRT* are expected to create new business opportunities in the existing infrastructure maintenance market and to offer business expansion opportunities into Asian countries that face similar problems

To achieve this, we will improve the standard of maintenance by using low-cost preventive maintenance while stressing the necessity to match the needs of infrastructure maintenance with the seeds of technical development, and developing new technologies into more attractive technologies that can be used on-site.

By achieving this, we aim at contributing to regional revitalization, as well as maintaining the important internal infrastructures to high standard while backing up a variety of regional

economic activities. Furthermore, we will create an attractive and ongoing maintenance market and build a base for overseas expansion based on successful regional examples.

Cabinet Office PD (Yozo Fujino)

■ Scale of budget: 3.13 billion yen (FY2017)

■ Implementation period: 5 years from FY2014

Sub-PD

Hajime Asama (University of Tokyo, Professor)
Yusaku Okada (Keio University, Professor) Chair: PD · Masaki Seki (Futaba Railways Industry, President and CEO)

Tadayuki Tazaki (Japan Construction Machinery and Construction Association, President)

- · Kenichi Tanaka (Mitsubishi Electric Corporation, Senior Engineer)
- · Kazuhiro Nishikawa (Public Works Research Institute, President)
- · Toshihiro Wakahara

Chair:

Secretariat:

(Shimizu Corporation, Chief Research Engineer)

SIP Infrastructure Promoting Committee

[Overall Coordination]

Secretariat: Cabinet Office

Members: Sub-PDs

Ministry of Internal Affairs and Communications,

Ministry of Education, Culture, Sports, Science and Technology, Ministry of Agriculture, Forestry and Fisheries,

Ministry of Economy, Trade and Industry,

Ministry of Land, Infrastructure, Transport and Tourism,

JST, NÉDO

Project Promoting Council

[Research and Development Promotion]

Members

Sub-PDs, advisory committee, Cabinet Office, Ministry of Internal Affairs and Communications, Ministry of Education, Culture, Sports, Science and Technology, Ministry of Ágriculture, Forestry and Fisheries, Ministry of Economy, Trade and Industry, Ministry of Land, Infrastructure, Transport and Tourism

JST NEDO

Research units Universities, National Research and Development Agencies, private enterprises, etc.

Maintenance, Renovation and Management

Overall Plan

To minimize the opportunity loss of regional revitalization resources such as logistics, service, and tourism, it is vital to implement efficient and highly economical maintenance, renovation, and management. This is important considering that infrastructures such as roads, railways, harbors, and airports are public assets and domain whose functions should always be maintained.

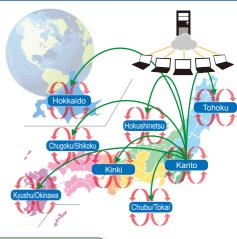
The following points are important in achieving the efficient maintenance and management of infrastructures, which are estimated to be worth a total of 800 trillion yen.

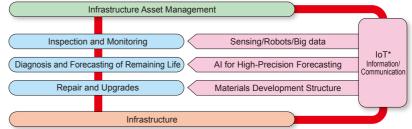
- Cooperation with a wide range of advanced technology fields including civil engineering and ICT/robotics technologies
- Coordinating technologies based on adaptations on-site
- Technical specification menu based on the various different situations of end users
- Technical managerial viewpoint including organization management to utilize the technology appropriately
- Sustainable support system for technical development

Without relying only on the results of technical development at each ministry, national research institute, university, and private company, an unprecedented cooperation system is also needed to achieve the above goals.

Further, we believe that we must actively roll out a new viewpoint concerning infrastructure maintenance through the related ministries and local governments to various users and residents.

This includes providing the society with new values created by appropriate maintenance of infrastructures such as the safety of users and our reputation as judged by users, as well as directly solving issues regarding the current methods of infrastructure maintenance.





Achieve Society 5.0, the world's first super smart society

*IoT: Internet of Things

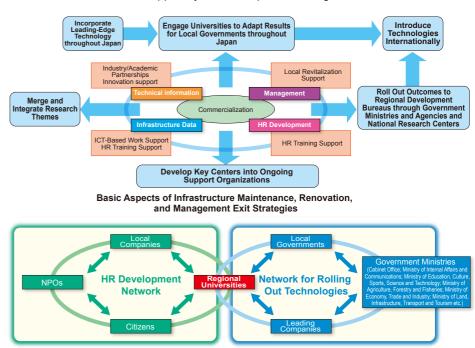
Exit Strategies

Since there is a diverse range of situations, targets, and technologies of infrastructure maintenance, we intend to implement infrastructure maintenance by optimally putting individual technical development together in the asset management phase. In the meantime, the development of IoT and other related technologies is remarkable, and construction of a platform that includes networked heterogeneous technologies, such as monitoring and sensing by robots and traveling vehicles, is rapidly becoming more of a real possibility. As a result, this has become a major strength that will allow us to drastically reform infrastructure maintenance. Therefore, we will advocate the promotion and cooperation with newly developed individual technologies by constructing an IoT platform to develop a scheme which will advance the integration of technologies through both asset management and the IoT platform.

As the base of this exit strategy, we will actively cooperate with key universities, regional universities, national research institutes, the Ministry of Agriculture, Forestry and Fisheries, the Ministry of Land, Infrastructure, Transport and Tourism, and local governments to create a unique framework for infrastructure related research. Specifically, we are considering the following business deployment patterns: "unique technological developments that have an individual theme," "deploying business to local governments through regional universities," "deploying business to the state administrative system through national research institutes," "establishing a permanent

organization system to support industries," and "exporting and globally deploying technology." Of these patterns, we place greatest importance on "custom-made technical implementation support that suits regional characteristics," and investigate a technical support system from the base institutes, a fund support system,

and the establishment of various technologies and sustainable support in local governments. In addition, we plan to implement a business model that will both help regional revitalization, and prepare an environment for business, by establishing a technical strategy plan based on reputation management.



Roll Out Infrastructure Maintenance and Renovation Management in the Regions





The 5 Research and Development Topics for Infrastructure

Maintenance

Cross-ministerial Strategic Innovation Promotion Program



Asset Management Technologies

Implement infrastructure management for the technologies produced from individual research results. Develop asset management technologies for efficient operations management making the most of limited financial and

human resources



Develop technologies that provide efficient, effective inspection and monitoring capabilities to assess infrastructure damage.





Companies

Structural Materials.

Mechanisms, Repairs,

Develop simulation technologies to

assess the deterioration mechanism

of structural materials; create a

structural deterioration forecast system.

and Reinforcement

Deterioration

Technologies

Information and Communications Technologies

Develop data management technologies utilizing enormous volume of information generated by infrastructure maintenance, management, renovation, and repair systems.

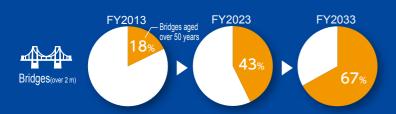
Robotics Technologies

(For Inspection, Disaster Measures, etc.)

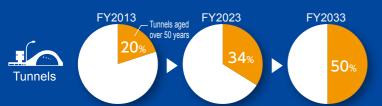
Develop robotics technologies to inspect, diagnose, operate, manage, and repair infrastructure elements efficiently and effectively; develop robots to perform surveys and excavation in dangerous situations such as disaster areas.



Implement for Domestic and Overseas Infrastructures

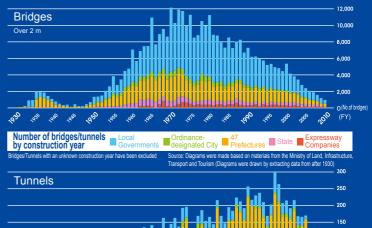


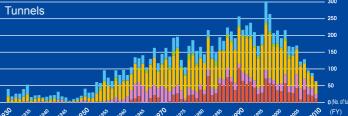
Transition ratio of bridges/tunnels over 50 years old -



Bridges/Tunnels with an unknown construction year have been excluded.

Source: Diagrams were made based on materials from the Ministry of Land, Infrastructure, Transport and Tourism



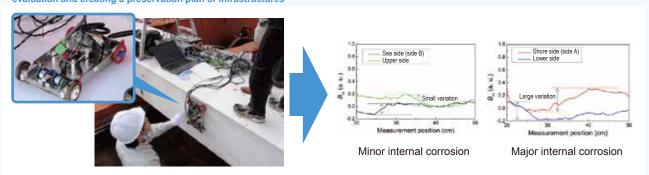


Inspection, Monitoring and Diagnostics Technologies



Ultrasensitive magnetic nondestructive testing for deterioration evaluation and creating a preservation plan of infrastructures

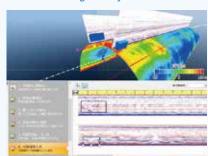
Inspection, monitoring and diagnostic technologies have been developed to fully estimate damages of civil infrastructures. R&D subjects such as an internal defect inspection technology using supersensitive magnetic nondestructive testing, an integrated diagnostic system using high-speed traveling noncontact radar, remote diagnostic technology using supersensitive near infra-red spectroscopy, a pavement inspection system. floor slab deterioration detection using onboard underground probe radar, and the displacement monitoring technique for infrastructures using Satellite SAR (Synthetic Aperture Radar) are in progress.



Inner defects inspection for tunnel lining using rapidly scannable non-contact radar and synthetic soundness diagnosis system

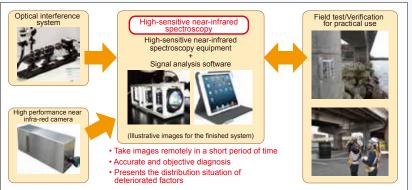




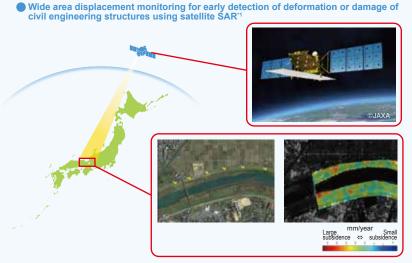


Illustrative images for inspection and diagnosis using non-contacting radar

Remote sensing of concrete structure with the high-sensitive near-infrared spectroscopy



Near infra-red imaging technology that can analyze the deteriorated components of concrete remotely



Efforts for site verification using Satellite SAR technology

*1 SAR: Synthetic Aperture Radar

Simple pavement inspection system utilizing an airport ground vehicle



A monitoring site demonstration on the runway of an airport

Detection of floor slab deterioration using the onboard underground probe radar



Detection of deteriorated portions inside a floor slab using an onboard high speed scan radar

Structural Materials, Deterioration Mechanisms, Repairs, and Reinforcement Technologies

Investigation of structural deterioration mechanisms and efficient maintenance systems

Concrete test block

Reinforcing bar

No cracks due to corrosion

Comparison of two-year exposure test results between normal carbon steel and anticorrosion steel (at Irabu Ohashi Bridge)

Anticorrosion steel Carbon steel Test surface

Concrete test block

Reinforcing bar Cracks due to corrosion Exposure test of a PC test beam deteriorated by ASR*2



Fly ash concrete

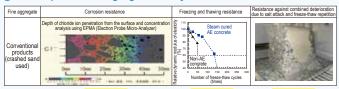


Concrete with no fly ash mixed

*2 ASR: Alkali Silica Reaction

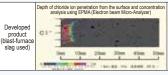
Extensive R&D activities have been in progress amidt urgent social demands in this category of the SIP project in oreder to develop simulation models for the deterioration mechanisms of structural materials and innovative estimation system for deterioration progress of infrastructures, to organize a core base for R&D of structural materials to develop effective maintenance technologies, and to promote the commercialization and wider application of precast members using highly-durable concrete for society

Precast products using high-durability concrete



5 times

300





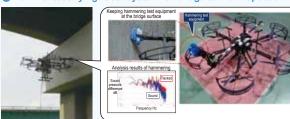


Robotics Technologies (For Inspection, Disaster Measures, etc.)



Various robots have been developed to inspect civil infrastructures, such as bridges and tunnels, safely and economically. At the same time, a wide range of R&D tasks are ongoing for a study of applicable structures for the introduction of robotics technologies, and establishing an integrated database to centrally manage the information for the effective utilization of robotics technologies. With these efforts, the implementation in society of robots for infrastructure maintenance is highly expectd.

Hammer test flying robot system for bridge/tunnel inspection



Hammer inspection multicopter

Multicopter with passive rotating spherical shell

Semi-submerged work robot using remote control

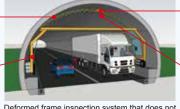


Transport robot for unmanned construction

The variable guide frame vehicle for inspection of tunnel







Deformed frame inspection system that does not hinder the transportation

Sensor for hammering and crack detection

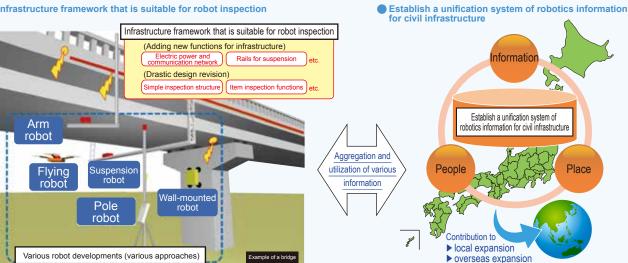




Crack Inspector

Hammering tester

Infrastructure framework that is suitable for robot inspection



Information and Communications **Technologies**



The main subject of R&D is to develop data management systems fully utilizing information and communication technologies (ICT) to take advantage of the enormous amount of information on maintenance, repair and renewal of civil infrastructures for contributing to the real application of advanced ICT for society. Specific R&D fields are data screening based on integrated large-scale sensor information for pavements and bridges and so on, data management enabling comprehensive control of a variety of information and data analysis and visualization technologies for making the stored data effectively applicable for real operation on-sites.

Research, development, and social implementation of screening technologies on pavement and bridges based on large-scale sensor information fusion toward preventive maintenance of infrastructure



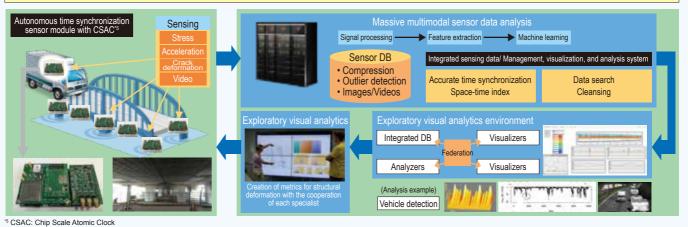
DRIMS (Measurement) is an iOS application that measures the condition and quality of the road surface using acceleration/angular velocity sensors installed in the iPhone/iPod touch

Integrated data management platform for civil Infrastructure sensing



viewer show the information independently *4 IRI:International Roughness Index Ride comfort index

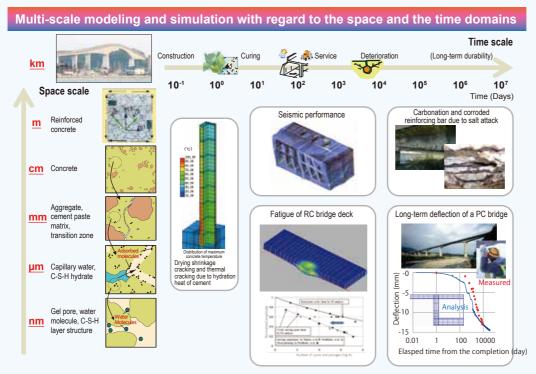
Support tool for road maintenance planning (for road administrators)



Asset Management Technologies

Along with real applications of R&D outcomes for society, SIP contributes to secured and safe infrastructures by cooperating with infrastructure administrators. The advanced technologies including non-destructive test methods and innovative numerical analysis have been developed for maintenance of road structures. In addition, SIP also proposes a highly sustainable asset management system from the viewpoints of contract scheme, human resource training, private sector utilization, and collaboration with the local residents to maintain enormous number of infrastructures which local governments should manage with a limited budget

Multi-scale analysis and data assimilation with non-destructive testing data







Project Organization -Infrastructure Maintenance, Renovation and Management-



Program Director



Yozo Fujino Yokohama National University

* In Japanese syllabary order * Affiliations are as of April 2018

Sub-PDs



University of Tokyo



Yusaku Okada



Futaba Railways Industry Co., Ltd.



Tadayuki Tazaki



Kenichi Tanaka Mitsubishi Electric Corporation



Kazuhiro Nishikawa Public Works Research Institute



Shimizu Corporation

Advisory Committee



Reiko Amano



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Osaka University Kyoto University University of Tokyo



National Institute for Land and



Okayama Concrete Technology Laboratory



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Chitoshi Miki Tokyo City University

Executive Secretaries





Takayuki Ishizuka



Makoto Kaneuji JST



Yoshinobu Nobuta



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Yuji Wada

Government Ministries



Ministry of Internal Affairs and Communications

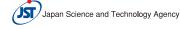
Ministry of Education, Culture, Sports, Science and Technology Ministry of Agriculture, Forestry and Fisheries Ministry of Economy, Trade and Industry

Ministry of Land, Infrastructure, Transport and Tourism

Funding Agencies / Related Ministry



Ministry of Land, Infrastructure, Transport and Tourism





New Energy and Industrial Technology Development Organization

Research Units

Universities

National Research and Development Agencies

Private Enterprises, etc.



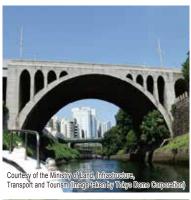


List of Research and Development Themes -Infrastructure Maintenance, Renovation and Management-



	No.	Research and Development Theme	Principal Investigator (Affiliation)
(1)		Interdisciplinary R&D of NDE Techniques for Innovative Maintenance	Principal Investigator (Affiliation) Masahiro Ishida(Public Works Research Institute)
		Development of the Laser Ultrasonic Visualization Technology for the Degradation Diagnosis of Steel Bridges	Junji Takatsubo(Tsukuba Technology Co., Ltd.)
		Ultrasensitive Magnetic Nondestructive Testing for Deterioration Evaluation and Creating a Preservation Plan of Infrastructures	Keiji Tsukada(Okayama University)
		R&D of Laser Directive Noncontact Diagnosis System for Maintaining Degraded Infrastructures	Katsumi Midorikawa(RIKEN)
		Development of Automatic Technology on Pavement & Embankment Survey and Evaluation	Atsushi Yashima(Gifu University)
		Non-destructive Inspection of Rebar Corrosion in Concrete	Kenji Ikushima(Tokyo University of A&T)
		R&D of Backscatter X-ray Imaging System for Concrete Inspection	Hiroyuki Toyokawa(AIST)
		R&D of Vibration Imaging Radar	Hitoshi Nohmi(Alouette Technology Inc.)
		Inner Defects Inspection for Tunnel Lining using Rapidly Scannable Non-contact Radar and Synthetic Soundness Diagnosis System	Toru Yasuda(Pacific Consultants Co.,Ltd.)
	10	Remote Sensing of Concrete Structure with the High-Sensitive Near-infrared Spectroscopy	Kazuhiro Tsuno(Shutoko Engineering Co., Ltd.)
		R&D of Learning-Type Hammering Echo Analysis Technology	Masahiro Murakawa(AIST)
	12	Inspection and Diagnosis System of Port Structure Using Radio Controlled Boat	Tetsuya Ogasawara(Penta-Ocean Construction Co., Ltd.)
	13	Development of the Special GPR Including a Chirp Radar in the Survey of a Cavity and a Settlement of the Back-fill Material	Shigeji Yamada(KAWASAKI Geological Engineering Co., Ltd.)
	14	Development of the Monitoring System for Port Facilities using Satellite and SONAR	Takeshi Nishihata(Penta-Ocean Construction Co., Ltd.)
	15	Monitoring by using Ground-Base Synthetic Aperture Radar and Array-type Ground Penetrating Radar	Motoyuki Sato(Tohoku University)
Inspection,	16	Monitoring System for a Round of Airport Paved Road Inspection, Utilizing a Technique for Detecting Cracks Automatically from High-resolution Images	Toru Hara(Alpha Product Co., Ltd.)
Monitoring and	17	R&D of the Crack Detection System for Runways with a 3D Camera and all Direction-moving Robot	Yasuo Kimura(NTT Advanced Technology Corp.)
Diagnostics	18	R&D of a Simplified System for Monitoring the Airport Pavement Surfaces Using Maintenance Vehicles	Yusho Ishikawa(The University of Tokyo)
Technologies	19	Development of Wide Area Displacement Monitoring for Early Detection of Deformation or Damage of Civil Engineering Structures using Satellite SAR	Masafumi Kondo(National Institute for Land and Infrastructure Management)
	20	Understanding the Scouring Situation by ALB (Airborne Laser Bathymetry)	Hiroaki Sakashita(PASCO Corp.)
	21	R&D of Monitoring System for Bridge Performance Assessment Based on Vibration Mode Analysis	Tadao Kawai(Osaka City University)
	22	Creation of Monitoring System using Equipment with Robotic Camera and etc. for Bridge Inspection	Yasuhisa Fujiwara(Sumitomo Mitsui Construction Co., Ltd.)
		R&D of Quantitative Evaluation System of Cracks on Distant Slabs by Digital Image Analysis Technology	Kenichi Horiguchi(Taisei Corp.)
		Field Validation of the Continuous Remote Monitoring System with Power saving Wireless Sensor	Hideshi Nishida(Omron Social Solutions Co., Ltd.)
			Minoru Murata(NEC Corp.)
		R&D of Monitoring System for Detecting Surface Failure by pore Pressure Sensor with Inclinometer	Yasunori Shoji(OYO Corp.)
		R&D of Early Warning Monitoring System of Slope Failure using Multi-point Tilt Change and Volumetric Water Content	Lin Wang(Chuo Kaihatsu Corp.)
		Mole (Small Animals) Hole Detection System Attached to Large Weeding Machine	Kiyoshi Suzuki(Aero Asahi Corp.)
		Electric Resistivity Monitoring System for the State of Water Contents in River Levee R&D of Monitoring System Including a Detection of River Levee Deformation	Hideki Saito(OYO Corp.) Shunsuke Sako(Japan Institute of Country-ology and Engineering, General Incorporated Foundation)
		* · · · · · ·	
-		Effective Use of Satellite SAR Observation for River Embankment	Takeshi Katayama(Infrastructure Development Institute)
-		Monitoring System for Internal State of River Levee utilizing Geophysical Exploration and Ground Water Observation	Akira Shinsei(OYO Corp.)
		Improvement for More Advanced and Efficient Road Structure Maintenance using Monitoring Technology	Atsushi Homma(Research Association for Infrastructure Monitoring System)
	34	Maintenance and Management of Social Infrastructure utilizing IT (Inspections, Diagnosis)	Ministry of Land, Infrastructure, Transport and Tourism
(2)	No.	Research and Development Theme	Principal Investigator (Affiliation)
Structural Materials, Deterioration Mechanisms,	35	Deterioration Mechanism of Infrastructures and Materials Technology for Efficient Maintenance	Koichi Tsuchiya(NIMS)
	36	Developing Hybrid Mechanoluminescence Materials for Visualization of Structural Health	Chao-Nan Xu(AIST)
Repairs, and Reinforcement	37	Technology of Repairing the Corrosion Damage and Deterioration to Steel Structures using Newly Developed Flame Coating Material	Kenji Higashi(Osaka Prefecture University)
Technologies		Precast Practical Application of PCa with Super-High Durability Concrete	Toshiki Ayano(Okayama University)
	NIo	Because and Davidenment Thems	Dringing Investigator (Affiliation)
	No.	Research and Development Theme Research, Development, and Social implementation of Screening Technologies on Pavement and Bridges based on Large-scale Sensor Information Fusion toward Preventive Maintenance of Infrastructure	Principal Investigator (Affiliation)
(3)			Masataka leiri(JIP Techno Science Co., Inc.)
Information and		R&D on Technologies for Collecting, Transmitting, and Processing Sensing Data of Civil Infrastructures (Underground Structures)	Shuichi Yoshino(NTT)
Communications Technologies		R&D of Integrated Data Management Platform for Civil Infrastructure Sensing	Jun Adachi(National Institute of Informatics)
recimologics		Development of Technologies on Wide Variety of Data Processing, Storage, Analysis and Application to Achieve Advanced Infrastructure Management	Isao Ueda(East Nippon Expressway Co., Ltd.)
	43	R&D on Data Store/Management/Utlization Technologies for a Variety of Data Relating to Maintenance and Replacement of Civil Infrastructures	Toshihiro Kujirai(Hitachi, Ltd.)
	No.	Research and Development Theme	Principal Investigator (Affiliation)
	44	Development of Infrastructure Inspection System using Semi-autonomous Multi-copter equipped with Flexible Electrostatic Adhesive Device	Tadahiro Hasegawa(Shibaura Institute of Technology)
	45	R&D of Diagnostic Technology Based on Measurement and Analysis by Multi-copter	Toshio Fukuda(Meijo University)
	46	Development of Intuitive Teleoperation Robot using the Human Measurement	01:1:004/1-11:1-)
	47		Shigeki Sugano(Waseda University)
		Development of Bridge Inspection Robot System Supported by the Provisional and Flexible Scaffolding Structure	Snigeкi Sugano(waseda University) Shigeo Hirose(HiBot Corp.)
		Development of Bridge Inspection Robot System Supported by the Provisional and Flexible Scaffolding Structure R&D of Flying Robot for Bridge/Tunnel Inspection	
(4)			Shigeo Hirose(HiBot Corp.)
Robotics	48 49	R&D of Flying Robot for Bridge/Tunnel Inspection	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.)
	48 49 50	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction)
Robotics	48 49 50 51	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University)
Robotics	48 49 50 51 52	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.)
Robotics	48 49 50 51 52 53	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area~	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shini'chi Yuta(New Unmanned Construction Technology Research Association)
Robotics	48 49 50 51 52 53 54	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute)
Robotics	48 49 50 51 52 53 54 55	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unnanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute)
Robotics Technologies	48 49 50 51 52 53 54 55 56	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism
Robotics Technologies	48 49 50 51 52 53 54 55 56 No.	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheledef Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area- Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No.	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No. 57	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shini'chi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No. 57 58	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shini'chi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No. 57 58 59	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of Junanned Construction Report Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shini'chi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No. 57 58 59 60	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and Implementation support team (including *)	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No. 57 58 59 60 Regii	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of Junanned Construction Report Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shini'chi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology)
Robotics Technologies	48 49 50 51 52 53 54 55 56 No. 57 58 59 60	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and Implementation support team (including *)	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization)
Robotics Technologies (5) Asset	48 49 50 51 52 53 54 55 56 No. 57 58 59 60 Regid	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of Bridge Inspection Support Robot System with Visual Observation and Hammering Test Devices Development of Unmanned Construction ~Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and Implementation support team (including *) Research on Regional Cooperation for Applications of Asset Management for Civil Infrastructures	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Isamu Nakajima(National Agriculture and Food Research Organization) Yasushi Takamatsu(Hokkaido University)
Robotics Technologies (5) Asset Management	48 49 50 51 52 53 54 55 56 No. 57 58 59 60 Regio 61 62 63	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and implementation support team (including *) Research on Regional Cooperation for Applications of Asset Management for Civil Infrastructures Conversion to a Regional-Autonomous System as Next-Generation Water Infrastructure Management	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization) Yasushi Takamatsu(Hokkaido University) Ken Ushijima(Hokkaido Research Organization)
Robotics Technologies (5) Asset	48 49 50 51 52 53 54 55 56 No. 57 58 59 60 Regid 61 62 63 64	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Ummanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Ummanned Construction ~Realization of Remote Operated Working System in Shallow Water Area~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and implementation support team (including *) Research on Regional Cooperation for Applications of Asset Management for Civil Infrastructures Conversion to a Regional-Autonomous System as Next-Generation Water Infrastructure Management Establishment and Promotion of the Tohoku Infrastructure Management Platform	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization) Yasushi Takamatsu(Hokkaido University) Ken Ushijima(Hokkaido Research Organization) Makoto Hisada(Tohoku University)
Robotics Technologies (5) Asset Management	48 49 50 51 52 53 54 55 56 No. 57 58 59 60 Regie 61 62 63 64 65	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Ummanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Ummanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development Onceming Mechanized Mobile Object Inspection Nethods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities onal implementation support team (including *) Research on Regional Cooperation for Applications of Asset Management for Civil Infrastructures Conversion to a Regional-Autonomous System as Next-Generation Water Infrastructure Management Establishment and Promotion of the Tohoku Infrastructure Management Platform Implementation of Effective SIP Maintenance Technologies by the ME Network	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization) Yasushi Takamatsu(Hokkaido University) Ken Ushijima(Hokkaido Research Organization) Makoto Hisada(Tohoku University) Keitetsu Rokugo(Gifu University)
Robotics Technologies (5) Asset Management	48 49 50 51 52 53 54 55 56 No. 57 58 60 61 62 63 64 65 66	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-Wheeled Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area~ Research and Development Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and implementation support team (including *) Research on Regional Cooperation for Applications of Asset Management for Civil Infrastructures Conversion to a Regional-Autonomous System as Next-Generation Water Infrastructure Management Establishment and Promotion of the Tohoku Infrastructure Management Platform Implementation of Effective SIP Maintenance Technologies by the ME Network Framework of Infrastructure Maintenance in Kansai/Hiroshima Regions and Actual Deployment of New Technologies Development of Civil Infrastructure Maintenance Systems for Local Governments Through Multi-Phased Diagnosis	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shini'chi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization) Yasushi Takamatsu(Hokkaido University) Ken Ushijima(Hokkaido Research Organization) Makoto Hisada(Tohoku University) Keitetsu Rokugo(Gifu University) Hitoshi Furuta(Kansai University) Tamotsu Kuroda(Tottori University)
Robotics Technologies (5) Asset Management	48 49 50 51 52 53 54 55 56 No. 57 58 60 61 62 63 64 65 66 67	R&D of Flying Robot for Bridge/Tunnel Inspection R&D of the Variable Guide Frame Vehicle for Inspection of Tunnel Development of Unmanned Aerial Vehicles for Observing and Hammering Aged Bridges at Short Range R&D of a Multicopter-based Inspection Robotic System with Visual Observation and Hammering Test Devices Development of a Bridge Inspection Support Robot System that uses Proximity-images with Geotag and a Two-wheeled Flying Robot New Development of Unmanned Construction ~ Realization of Remote Operated Working System in Shallow Water Area ~ Research and Development of Infrastructure Structures and Inspection Devices for Advanced Inspection of Civil Infrastructure Research and Development Concerning Mechanized Mobile Object Inspection Methods and Structure Forms that Aim to Save Energy and Improve Accuracy of Inspection Establish an Unification System of Robotics Information for Civil Infrastructure Research and Development Theme Global R&D on the Management Cycle of Road Infrastructures Resolution of Early-aged Deterioration Mechanism & Development of Total Management System Based on Evaluation for Material and Structure Quality Performance Development of Life-cycle Management System for Port and Harbour Facilities - Integrated Framework from Inspection to Assessment R&D of Development of Strategic Asset Management Technologies for Trunk Agricultural Water Facilities and implementation support team (including *) Research on Regional Cooperation for Applications of Asset Management for Civil Infrastructures Conversion to a Regional-Autonomous System as Next-Generation Water Infrastructure Management Establishment and Promotion of the Tohoku Infrastructure Management Platform Implementation of Effective SIP Maintenance Technologies by the ME Network Framework of Infrastructure Maintenance in Kansai/Hiroshima Regions and Actual Deployment of New Technologies Development of Civil Infrastructure Maintenance Systems Focusing on Risks of Serious Accidents	Shigeo Hirose(HiBot Corp.) Toshihiro Nishizawa(NEC Corp.) Satoru Nakamura(Tokyu Construction) Kazunori Ohno(Tohoku University) Hideki Wada"(Shinnippon Nondestructive Inspection Co.,Ltd.) Naoyuki Sawasaki(Fujitsu Ltd.) Shinichi Yuta(New Unmanned Construction Technology Research Association) Kenichi Fujino(Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) (Changed to Joint Research with the Public Works Research Institute) Ministry of Land, Infrastructure, Transport and Tourism Principal Investigator (Affiliation) Koichi Maekawa(The University of Tokyo) Kazuyuki Torii(Kanazawa University) Ema Kato(National Institute of Maritime, Port and Aviation Technology) Isamu Nakajima(National Agriculture and Food Research Organization) Yasushi Takamatsu(Hokkaido University) Ken Ushijima(Hokkaido Research Organization) Makoto Hisada(Tohoku University) Keitetsu Rokugo(Gifu University) Hitoshi Furuta(Kansai University) Tamotsu Kuroda(Tottori University)
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Cross-ministerial Strategic Innovation Promotion Program (SIP) Website (Cabinet Office) http://www8.cao.go.jp/cstp/panhu/sip_english/sip_en.html





