## **Upcycling Tree Branches into Architecture and Design**

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### 1. Collaborative Design and Fabrication (ACM TEI)



### 2. Human-in-the-loop Fabrication



### Instead of Recycle, Upcycle

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While recycling takes consumer products and
breasts them into this and powders, upcycling
takes resources almost as they are and gives them
better purposes, converting them into more useful
objects than what they originally were. Recycling
plattic bags, as a example, is to melt them and
form new plasting bags. Upcycling plastic bags is
to use them a sixte or lamp shades. Traditional architecture naturally upcycle resources. In this case,
the materials is not necessarily consumer products
but natural resources, such as woods and rocks.
We often find curved wooden beams in Japanese
farmbouse called Minka. It is difficult to use such
materials with original forms in modern buildings.

In such traditional architecture, a master build-In such traditional architecture, a master build-er was in charged of selecting right materials and placing them in right parts, called "tektraitekisho" in Japanese. Nowadays, design process is more systematized with standardized parts due to legal regulations, however, curvy beams and raw surface of timbers are still in use but rare.



### Here Comes Tree Branches

Tree branches accounts for 25% of a tree but they are chipped and burned. We take them as an ex-ample resource we can upcyle with modern infor-mation and communication technologies. With minimum processing of lap joints on them, we can transform them into building materials.



### Koriki

Koriki

Koriki is a traditional sustainable forestry in Japan since 300 years ago in Shlikoku island where broadleawed forests have been sustainably utilized. Koriki has received National Forestry Heritagein 2018 for its unique cutting patterns, as well as its selection cutting to balance various ages and species of trees. This selection cutting to balance warloss ages and species of trees. This selection cutting produces small-sized trees and branches as bi-products of the process. Currently the application is limited to fire logs and mushroom beds, which are not profitable, thus it is difficult to keep this traditional forestry management activity. Nowadays only few are in practice. Searching for high-valued applications to maintain the traditional forestry is indispensable. We received 200 branches with 4-7 cm and cut in a same length.



## 1. Collaborative Design and Fabrication (ACM TEI)

### Concept: Roofing Together

Learning from traditional architecture in Japan again, Yui is a traditional social system to work together and help each other in rural villages. In Shirakawa village, Yui is used for replacement of the thatched roots since it is huge and very steeply sloped therefore needs a tremendous efforts. Thanks for hundreds of community members, the roofing process can be finished within two days.



Proto content of this integritation because in the many construc-tion in Likewise gathering and participating construc-tion in Yui, we developed an online game ap-plication that less multiple non-expert users explore layouts of tree branches. The goal of the game is to connect predefined target points on a frame with a limited number of branches. Users can pick a branch from the waitable set displayed on the bottom and create layouts by moving, rotating, and mirroring branches. The user continuously receives visual feedback and a score, midline by user to a feasible design. The score, guiding the user to a feasible design. The game is completed when all the target points are connected.

### Workflow from Collect and Scan to Fabricate









Aiming for upcycling tree branches by everyone, we devel-oped a workflow mediating man-ual labor work and digital pro-cesses, consisting of mainly four steps: Collect, Sean, Design, and Fabricate. Firstly, we physically scan them. The scanned branches are commutationally connected scan them. The scanned branch are computationally connected and the resulting layout is ama-lyzed regarding feasibility and fabricatability. Finally the inter-sections are converted to joints and milled by a typical 3-axis CNC router. The workflow was validated through two projects with difference approaches.

### Preliminary Study



Demo Booth at SXSW



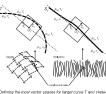
As a preliminary study of the developed worldlow from scan to fabricate, we organized a design and labrication worldshop to examine the feasibility of our system. It was bosted in a public community house close to a forest in participants were four children (aged 4.7, 9a and 10) and two parents. We set the goal to create a screen wall (2000 mm x 900 mm) divided into 8 sub-frames (500 mm x 450 mm).

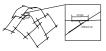
is that participants preferred to complete a large wall without subdividing frames. In this case study, a 2D screen wall with a single large frame was designed and built to exhibit at SXSW (South by South West).

## 2. Human-in-the-loop Fabrication

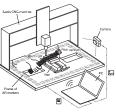
# Branch Matching

Reciprocal Pattern and

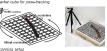


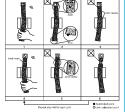


## Human-in-the-loop Fabrication

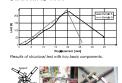


Material Preparation

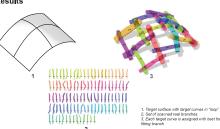




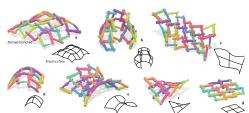
### Structural Test



### Results







### Target Surface to Target Curves

The target surface is a user-defined parametric surface with a limit of curvature. It is translated to a network of target curves to be assigned with branches. The network pattern creates "toops" which contributes to the overall stability of the joints.

Matching
The goal is to match real branches to the target curves of the construction pattern. The strategy is to first search for the best pose of every branch skeleton to every target curve, to create a matrix of the cost of every combination. Then we can assign a unique branch to each target, so that the sum of the fit values is minimized, by implementing the Hungarian Algorithm. We aim to position each branch skeleton Sto each target curve? Is othat the directions of the two curves are algenced, and so that the strongest curvatures he in the same plane. Local coordinate vectors are first defined for each curve. Then we use these to make the affine transformation to orient S to T. With these criteria there are 4 positions of every pair - mirroring and lipping the branch which maintaining the direction. The length of the branch is also considered. We first coravely try the placement at every 5 cm, and then pick the closest fit and refine the pose at every 1 cm. Now we can select the best pose out of the four orientations, and the multiple segments for each target-skeleton pair. The cost is calculated as the average distance between joint points and the closest points on the skeleton curve.

### Optimizing by Relaxing

There is a need to further negotiate between ideal target shape and existing material to make the surface fabricatable. The branch network is relaxed with a dynamic model, with the goal of minimizing and equalizing the distance where branches are supposed to intersect and make a joint.

Joint
The geometries of cross lap joints are calculated at each intersection. The joint is customized to the skeleton angles and the local radiuses. The cutting paths are defined from these outlines, with the milling bit radius as a variable parameter, Milling paths are automatically generated and exported as GCode.

FAUTICATION SETUP
Each joint needs to be milled out from a specific side of the branch, defined by its position in the design layout. A 3-axis CNC machine can, however, only approach the material from above. We slow this by a human-in-the-loop process. A type of saxis capability is achieved by asking the user to place the branch with the intended cutting area facing upwards, aligning with the Z-axis of the CNC-machine.

### Audio Feedback

Audio Feedback

To help position the branch correctly, the user receives audio feedback in form speech and a beeping sound which intensifies as the branch gets closer to the correct pose. For each joint, the user holds on to the branch and finish the "ofl" and "pitch" of the pose with help of audio feedback. The the user fixes the branch in a vise. The milling path is informed by the final position, and sent to the machine.