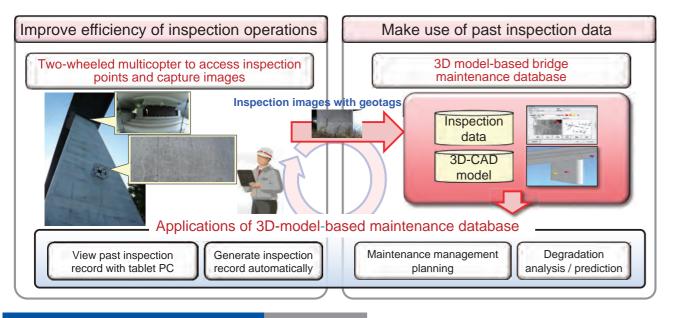


Principal Investigator Naoyuki Sawasaki (Fujitsu Limited)

Fujitsu Limited, Nagoya Institute of Technology, Tokyo University, Hokkaido University, Collaborative Research Groups Docon Co. Limited

R&D Objectives and Subjects

We propose a bridge inspection robot system that captures proximity images and a 3D-model-based maintenance database to link inspection data with 3D models. Our system can make on-site bridge inspections more efficient and support bridge maintenance operations.

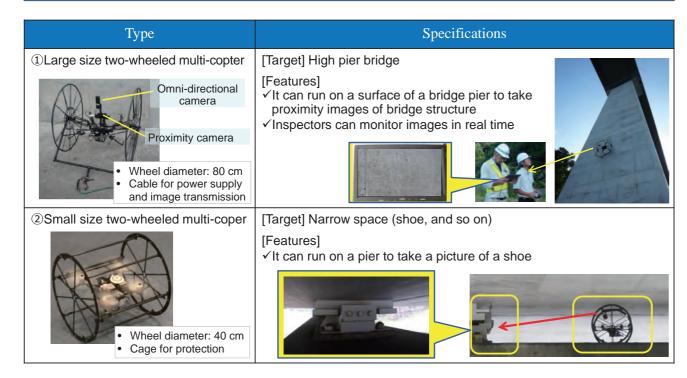


Current Accomplishments (1/2)

Fea

We prototyped two-wheeled multi-copters for bridge inspection.

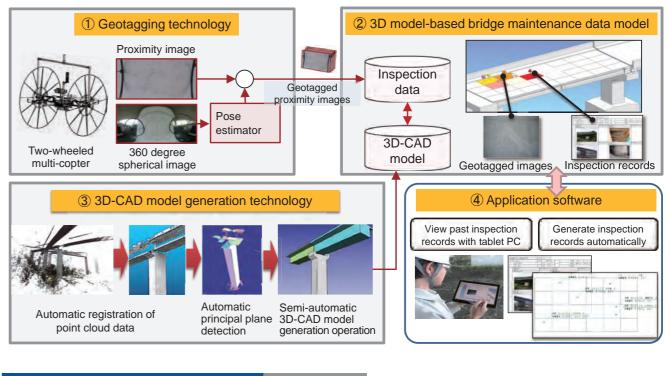
atures	 It can take proximity-images with constant distance to bridge surface.
	 It is robust against windy conditions because of skin friction of the wheels.





Current Accomplishments (2/2)

We prototyped a 3D model-based bridge maintenance system for long-term use. ① Geotagging technology based on SFM (Structure from Motion) using 360 degree spherical camera (2) A 3D model-based bridge maintenance data model which is as extension of the ISO standard of the 3D-CAD model 3 Semi-automatic 3D-CAD model generation technology (4) Application software for viewing past inspection data on 3D-CAD models using tablet PCs



Goals

- Development of multi-copters for taking proximity images of high pier bridges • Wind-resistant stability available for practical use, mechanism and a control system for safe remote control
- Utilization of inspection data to make bridge maintenance tasks more efficient • Establishment of basic technology for high level utilization of inspection data

