

Higher-order Methods for Simulating Light Propagation and Light-Matter Interaction in Nano-Photonic Systems

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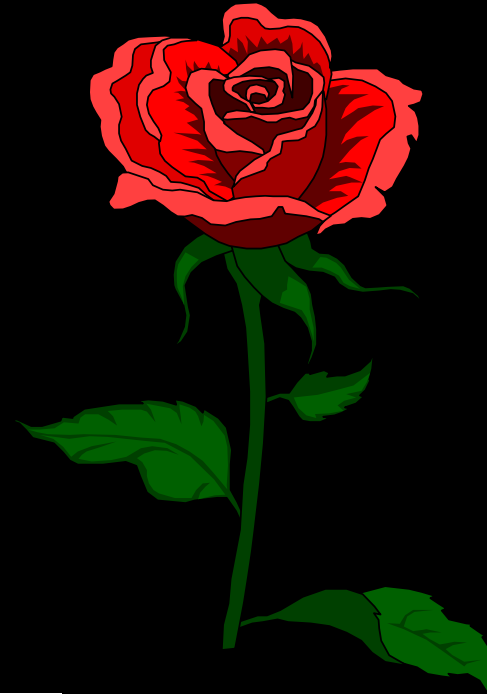
DFG-Center for
Functional Nanostructures
and
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Optics & Photonics

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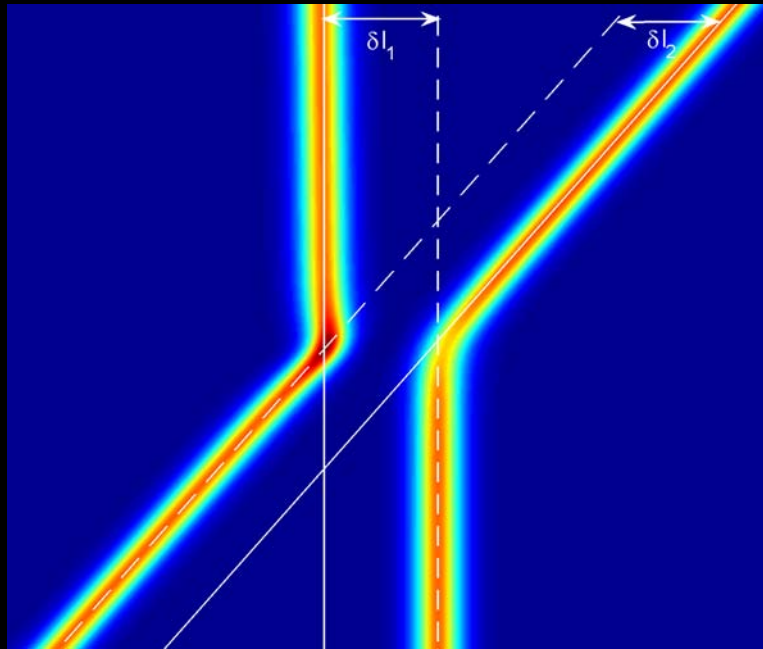
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Jan Gieseler
Martin Pototschnig*
Kai Stannigel



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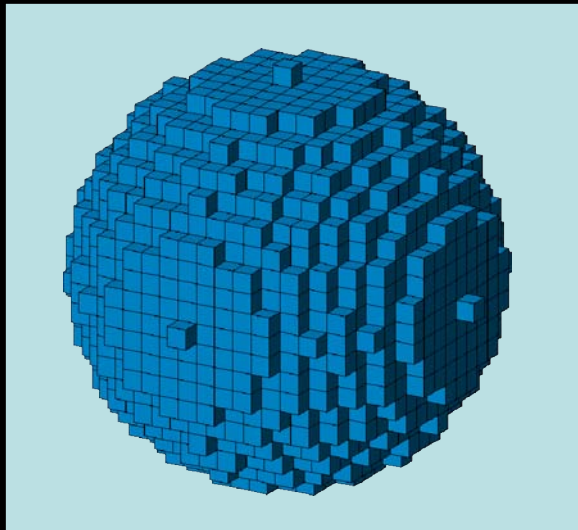
Motivation



Soliton collision in a
fiber Bragg grating

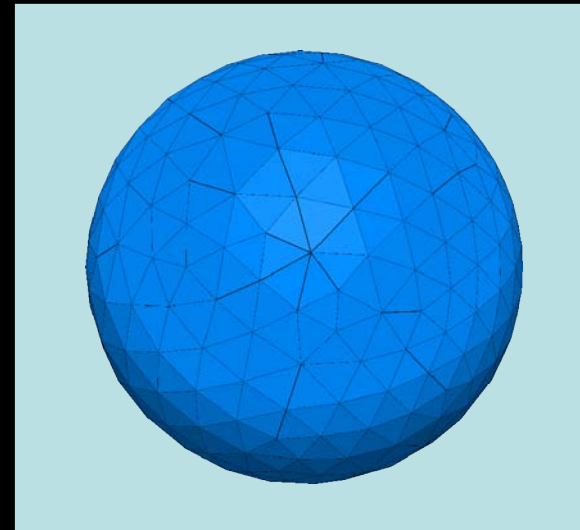
- Linear, nonlinear and quantum optical problems in nano-phonic systems involve multiple time and length scales
- This requires accurate, stable, and efficient solvers for linear and nonlinear Maxwell's equation and coupled systems

Motivation: Standard Approaches



FDTD-Method

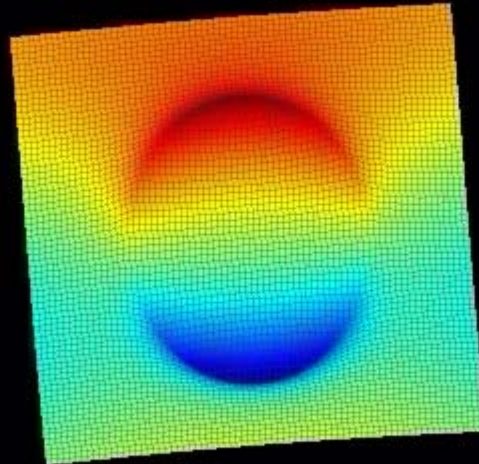
- Discretization on Yee-grid
- 2nd order in space and time
- Efficient and easy to implement



Finite-Element-Method

- Discretization on unstructured grids
- Higher-order in space
- Frequency-domain preferred

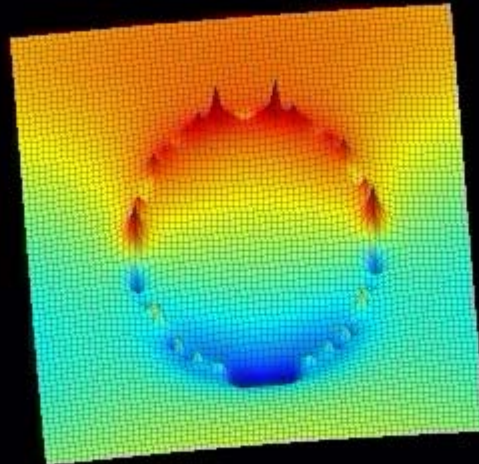
Motivation: Do not trust Computers I



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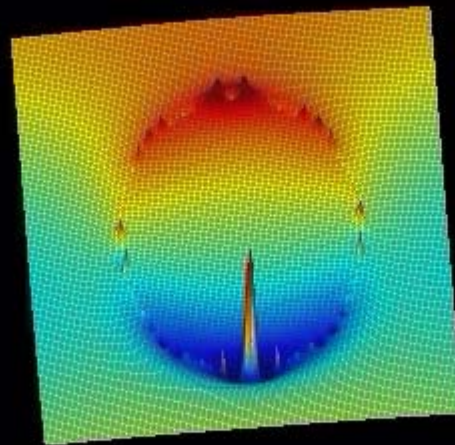
Motivation: Do not trust Computers II



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Motivation: Do not trust Computers III



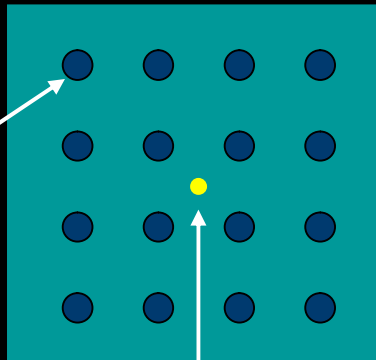
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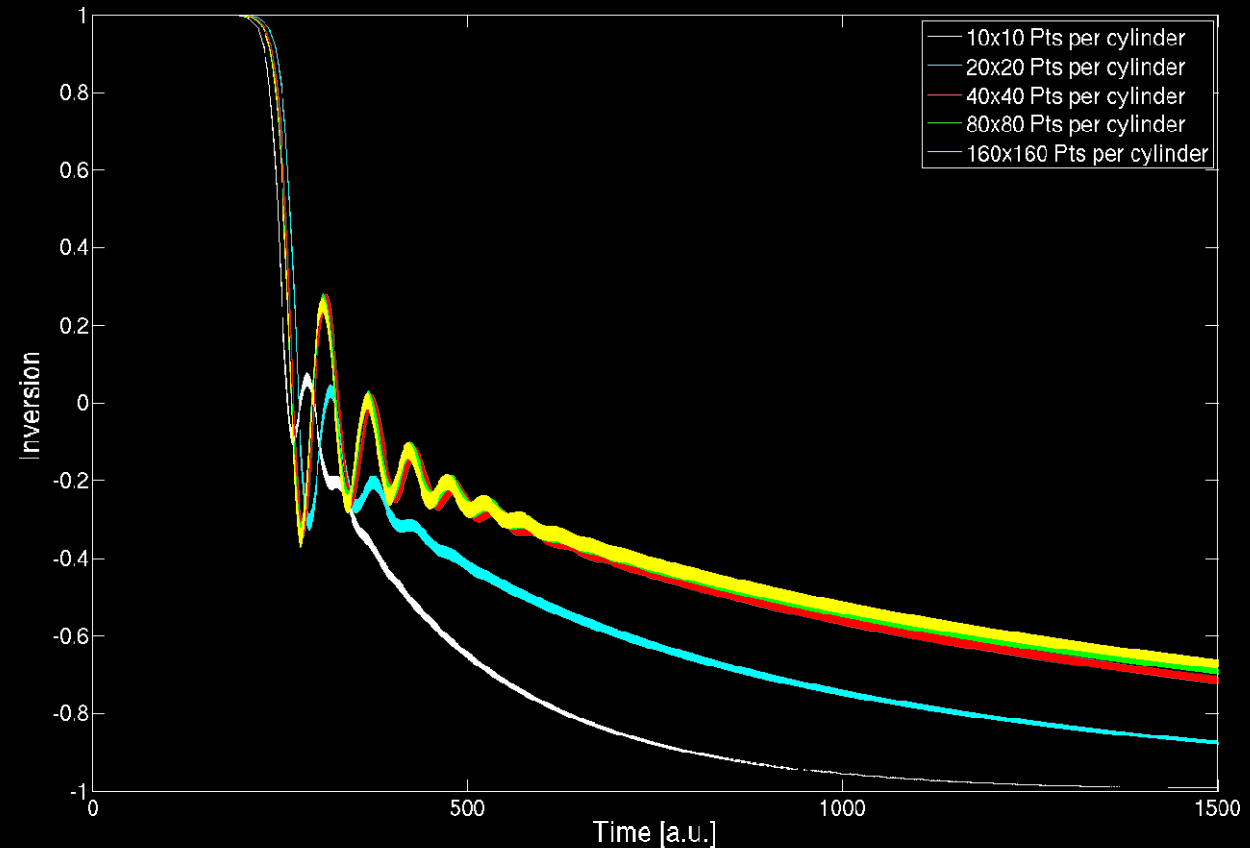
Motivation: Do not trust Computers IV

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Silicon rods in air



Two-level atom
(initially excited)



Outline

- The Krylov-Subspace/Discontinuous Galerkin Approach
 - How the method works and performs
 - Advanced spatial discretization
- Extension to Nonlinear & Coupled Systems
 - Lawson-Transformation and Rosenbruck-Wanner solvers
 - Performance
- Examples and Applications
 - Spontaneous emission in photonic crystals
 - Plasmonic structures



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The Krylov-Subspace Method

- Maxwell equations in Schrödinger form

$$\underbrace{\frac{\partial}{\partial t} \begin{pmatrix} \vec{E} \\ \vec{H} \end{pmatrix}}_{\Psi(t)} = \underbrace{\begin{pmatrix} -\sigma_{\text{el}} & \frac{1}{\epsilon(\vec{r})} \nabla \times \\ -\frac{1}{\mu(\vec{r})} \nabla \times & -\sigma_{\text{mag}} \end{pmatrix}}_{\mathcal{H}} \begin{pmatrix} \vec{E} \\ \vec{H} \end{pmatrix} - \underbrace{\begin{pmatrix} \vec{J}_{\text{el}}(t) \\ \vec{J}_{\text{mag}}(t) \end{pmatrix}}_{\mathbf{J}(t)}$$

- A formal solution of is given by

$$\Psi(t) = e^{t\mathcal{H}}\Psi(0) + \int_0^t e^{(\tau-t)\mathcal{H}}\mathbf{J}(s)d\tau$$

The Krylov-Subspace Method

- Discretization of $\Psi(t)$ and \mathcal{H} (e.g. on a Yee-Grid)
à Very large but sparse matrix H
- Matrix-Vector-Products $H\Psi$ are feasible
- We do not require the full matrix e^{tH} , only its action on a vector: $e^{tH}\Psi$
- We do not want any restrictions on the properties of the matrix H (such as skew-symmetry etc.)



The Krylov-Subspace Method

- Build up the Krylov Subspace

$$K_m = \text{span}\{\psi_0, H\psi_0, H^2\psi_0, \dots, H^{m-1}\psi_0\}$$

- Ortho-normalize the basis by Arnoldi-method

à Orthogonal Basis V_m

- Obtain projection of H onto V_m

$$H_m = V_m^T \mathcal{H} V_m$$

- The number of basis vectors can be small ($m \sim 10$)



The Krylov-Subspace Method

- The key approximation then is

$$e^{tH}\Psi \approx \|\Psi_0\| V_m e^{tH_m} e_1$$

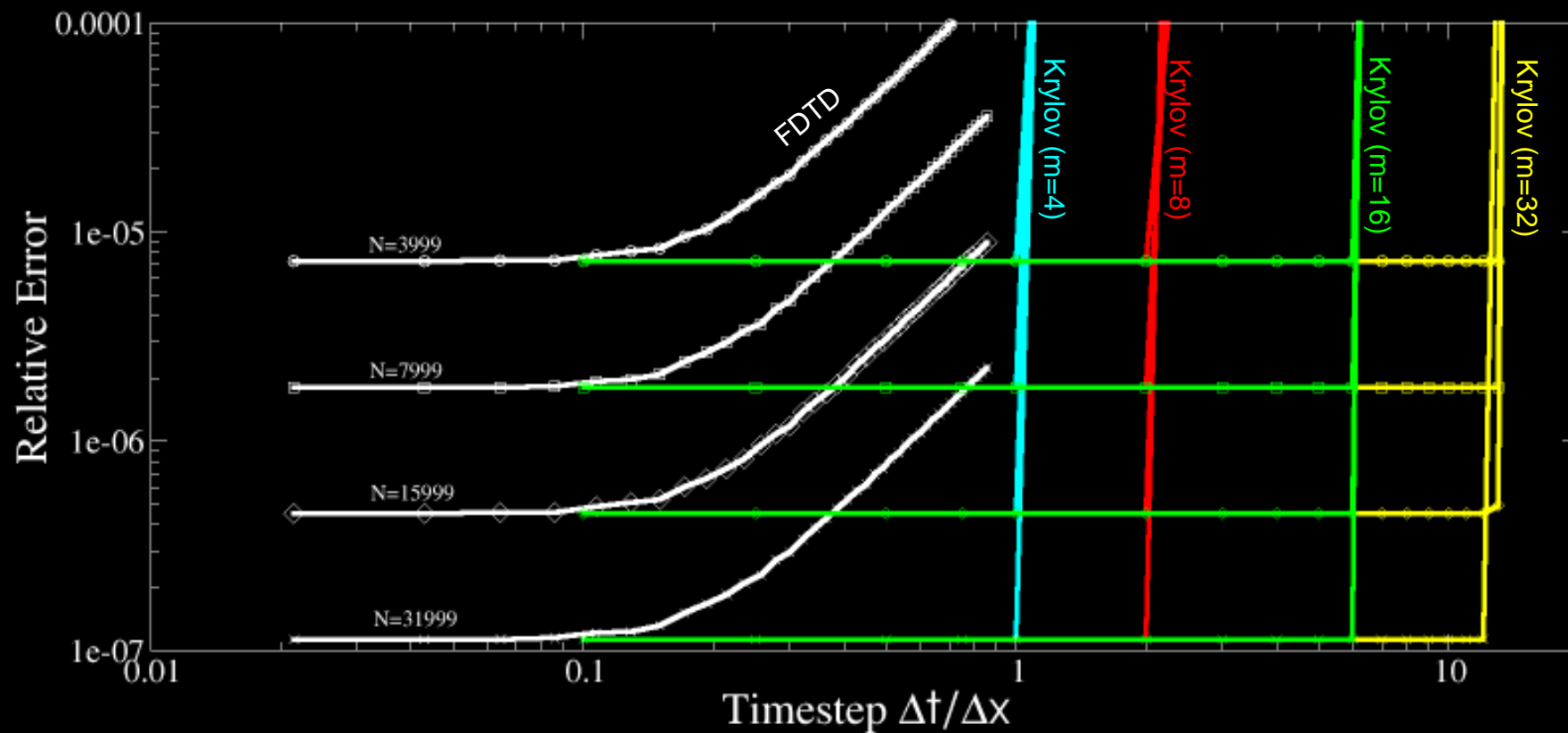
- Works for arbitrary matrices H
- The accuracy of the method is at least $O(t^m)$
- Memory usage: $(m+1)/2$ relative to FDTD

J. Niegemann, L. Tkeshelashvili, and K. Busch,
J. Comput. Theor. Nanosci. 4, 627 (2007)



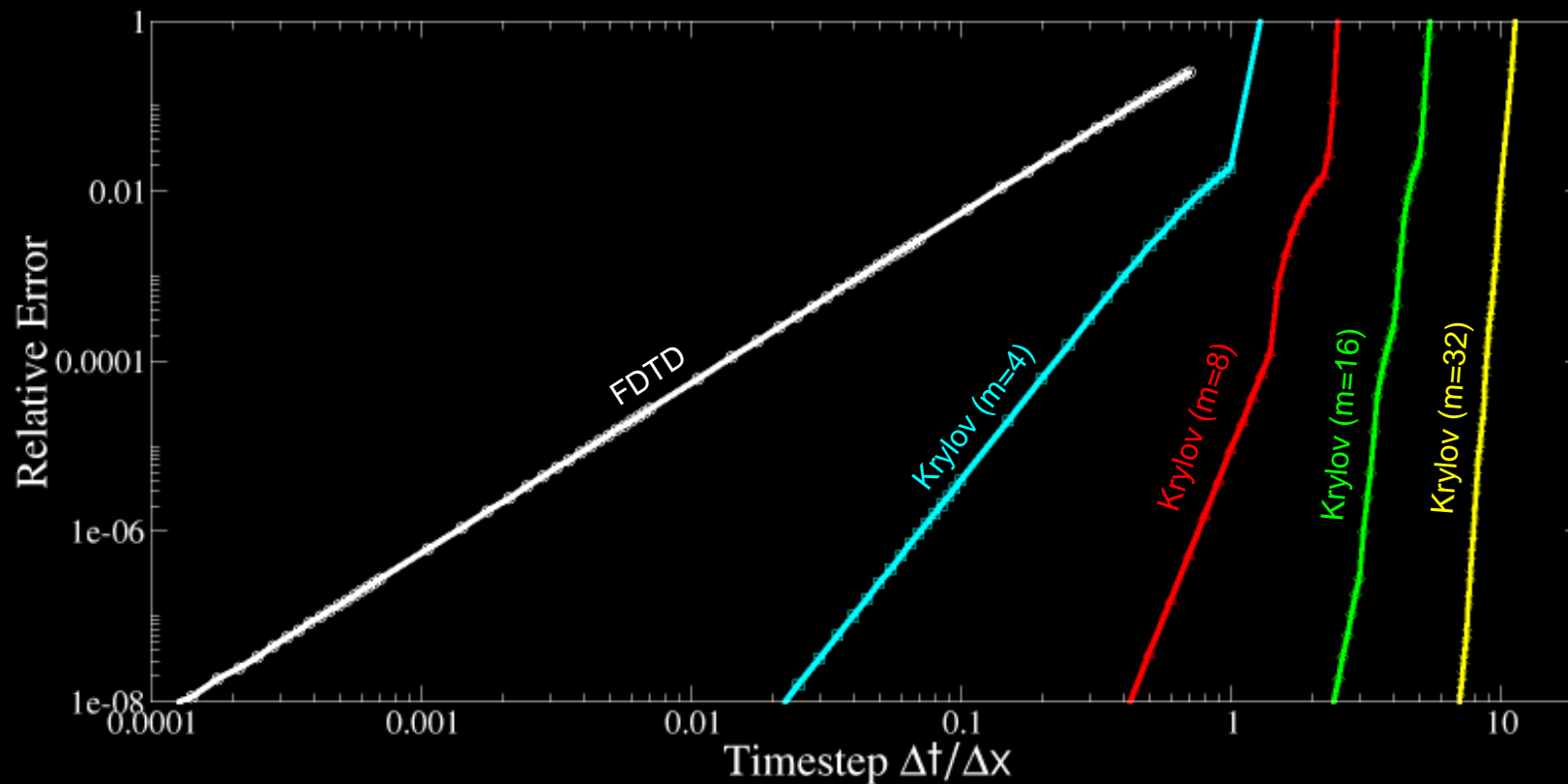
Comparison of Performance (1D)

- The method allows much larger time steps



Comparison of Performance (2D)

- In a 2D system, the effect is even more pronounced



Important Add-Ons - Via ADEs

- Dispersive Materials
 - Drude-, Lorentz-, Debye-Model
 - Sellmaier-type Models
- Sources
- Open Systems: Complex frequency shifted PMLs



Material Dispersion via ADEs

- All typical analytic dispersion relations (Drude, Lorentz, Debye) can be implemented via ADEs.
- Experimental dispersion fitted by combined (multiple) Lorentz- or Drude-terms.
- Example: $\epsilon(\omega) = \epsilon_\infty + \frac{\omega_0^2 \Delta\epsilon}{\omega_0^2 + 2i\omega\delta - \omega^2}$ (Single Lorentz-term)

$$\frac{\partial}{\partial t} \begin{pmatrix} \mathbf{E} \\ \mathbf{H} \\ \mathbf{j} \\ \mathbf{k} \end{pmatrix} = \begin{pmatrix} -\sigma_e & \frac{1}{\epsilon_\infty} \nabla \times & -\frac{1}{\epsilon_\infty} & 0 \\ -\frac{1}{\mu} \nabla \times & -\sigma_m & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{\omega_0^2 \Delta\epsilon}{\epsilon_\infty} \nabla \times & -\omega_0^2 \left(1 + \frac{\Delta\epsilon}{\epsilon_\infty}\right) & -2\delta \end{pmatrix} \begin{pmatrix} \mathbf{E} \\ \mathbf{H} \\ \mathbf{j} \\ \mathbf{k} \end{pmatrix}$$

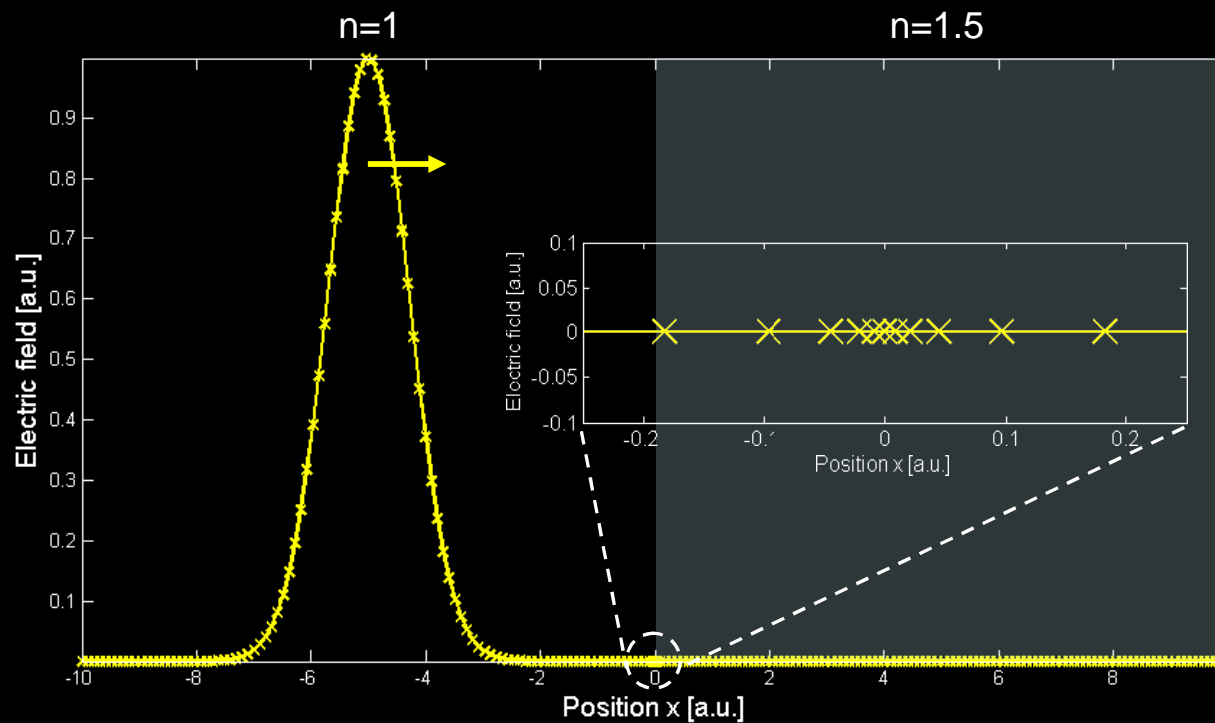
Advanced Spatial Discretization

- With the Krylov-subspace method, accuracy of time-integration can be chosen arbitrarily
- Problem: Error from the spatial discretization is limiting the total accuracy
 - à Higher order stencils
 - à Still only 2nd order in the presence of boundaries
- Possible solution: Adaptive grid refinement around boundaries



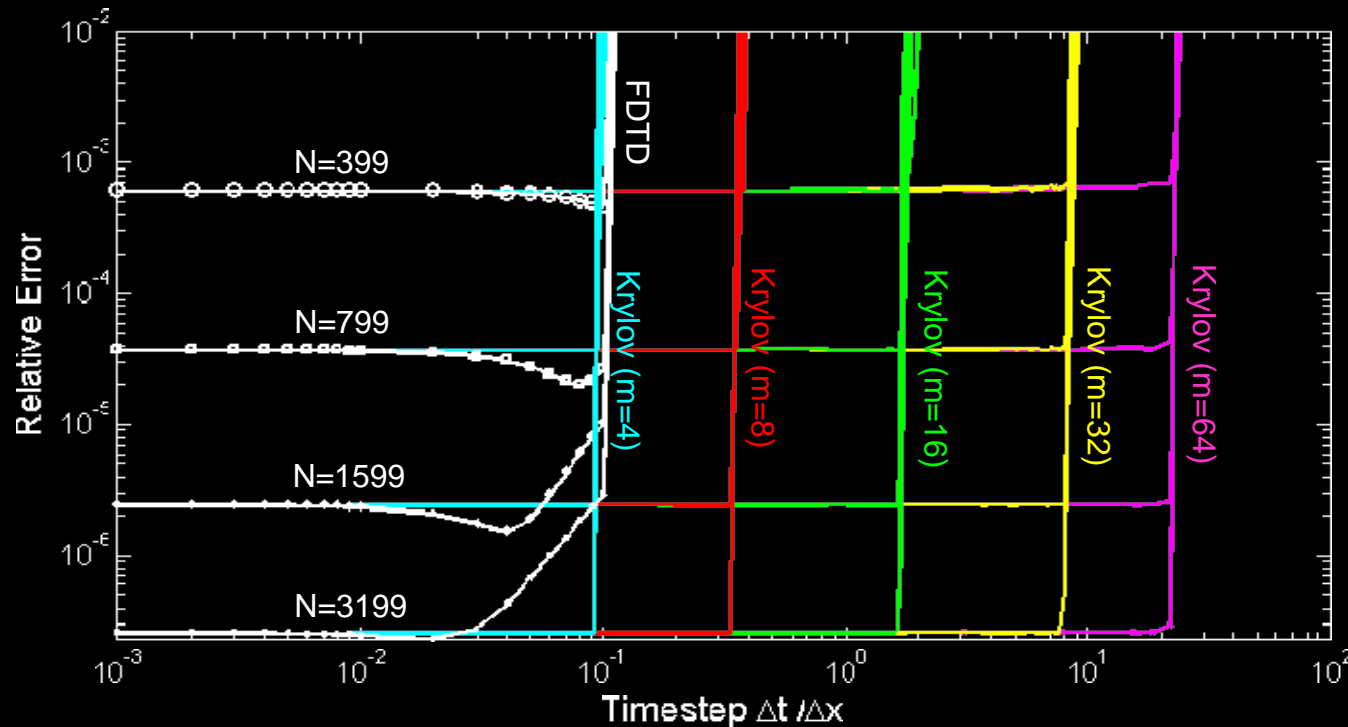
Unstructured Grid in 1D

- Adapt the grid so the point density is higher around the material boundaries



Unstructured Grid Performance (1D)

- 4th-order stencil and adaptive grids: 4th order is maintained in the presence of material boundaries



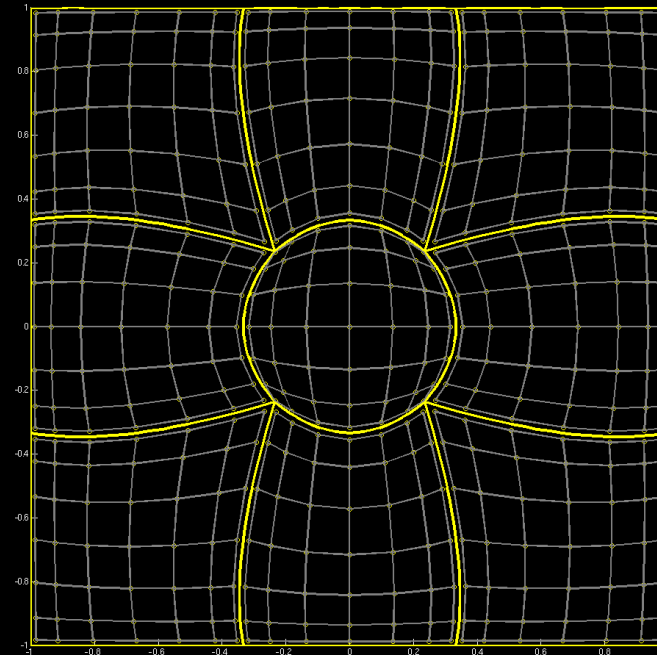
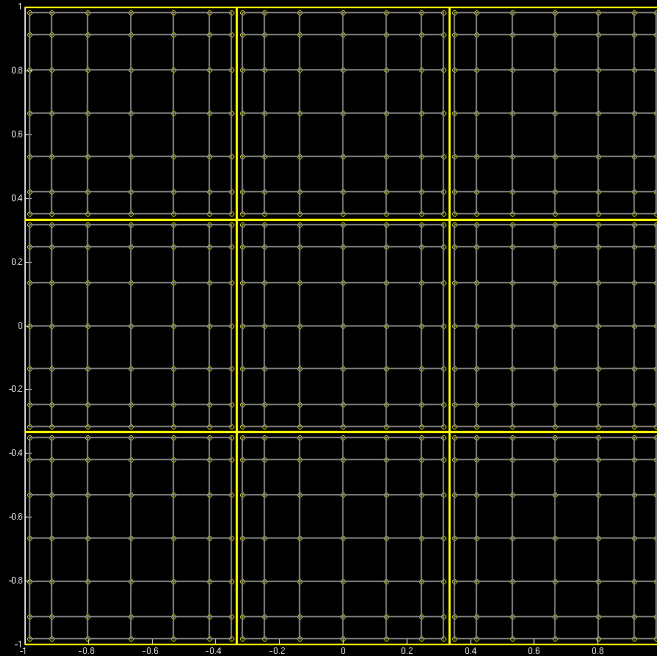
K. Busch et al.,
physica status solidi (b) 244, 3479 (2007)

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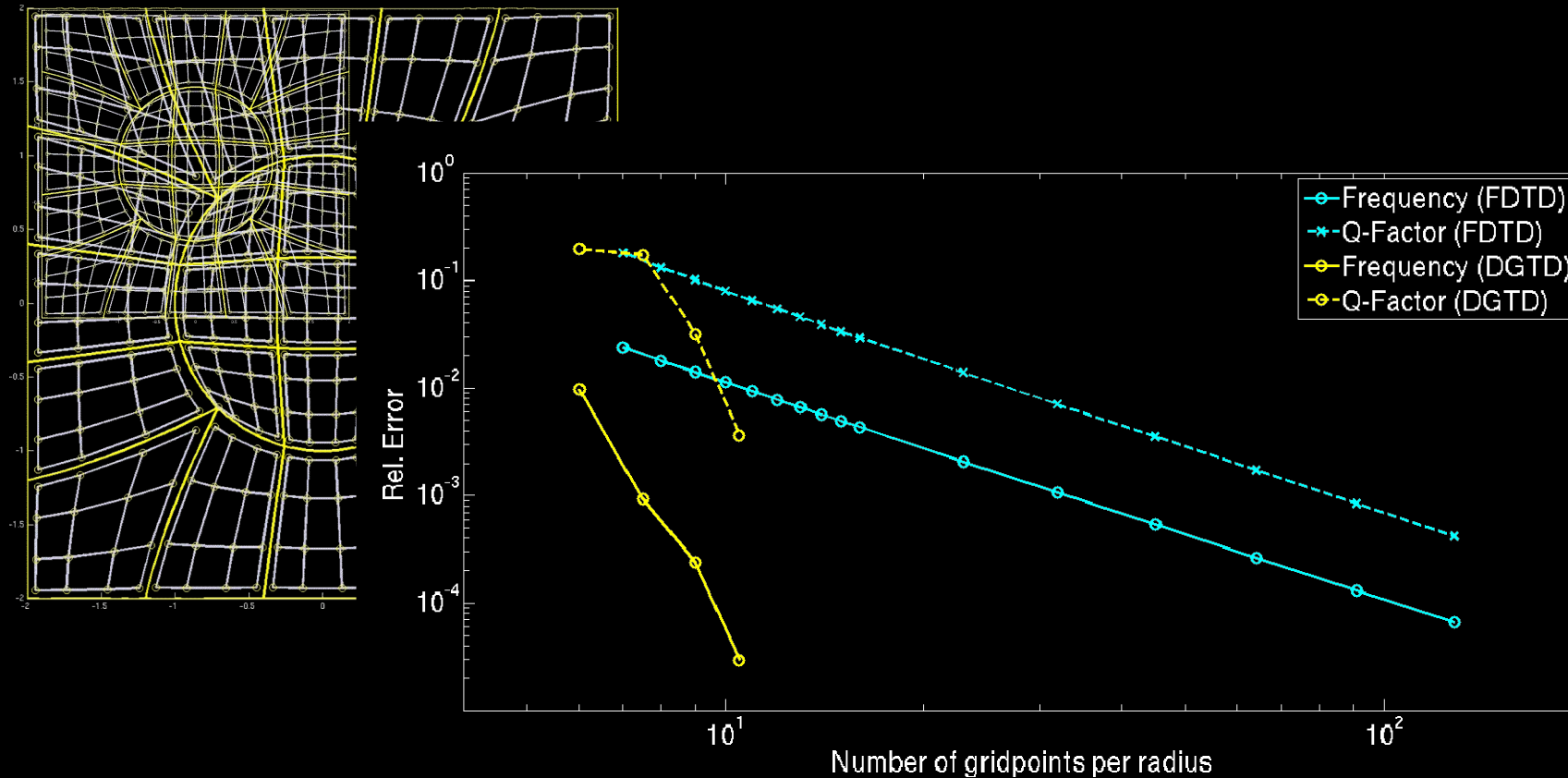
Unstructured Grids in 2D/3D



- Discontinuous Galerkin finite element technique (borrowed from hydrodynamics)

Results on Unstructured Grids (2D)

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Extension to Nonlinear Systems

- The method can be extended to nonlinear systems

$$\frac{\partial}{\partial t} \Psi = H \Psi + N[\Psi]$$

- Lawson-Transformation:
 - à H is the linear part of the nonlinear system
- Rosenbruck-Wanner solvers:
 - à H is the Jacobian of the nonlinear system



Extension to Nonlinear Systems

$$\frac{\partial}{\partial t} \Psi = H \Psi + N[\Psi]$$

- Lawson-Transformation

$$e^{-tH} \frac{\partial}{\partial t} \Psi = e^{-tH} (H \Psi + N[\Psi])$$

$$\frac{\partial}{\partial t} \underbrace{(e^{-tH} \Psi)}_{\mathbf{A}} = e^{-tH} N[\Psi]$$

$$\frac{\partial}{\partial t} \mathbf{A} = \underbrace{e^{-tH} N[e^{tH} \mathbf{A}]}_{F[\mathbf{A}]}$$



Extension to Nonlinear Systems

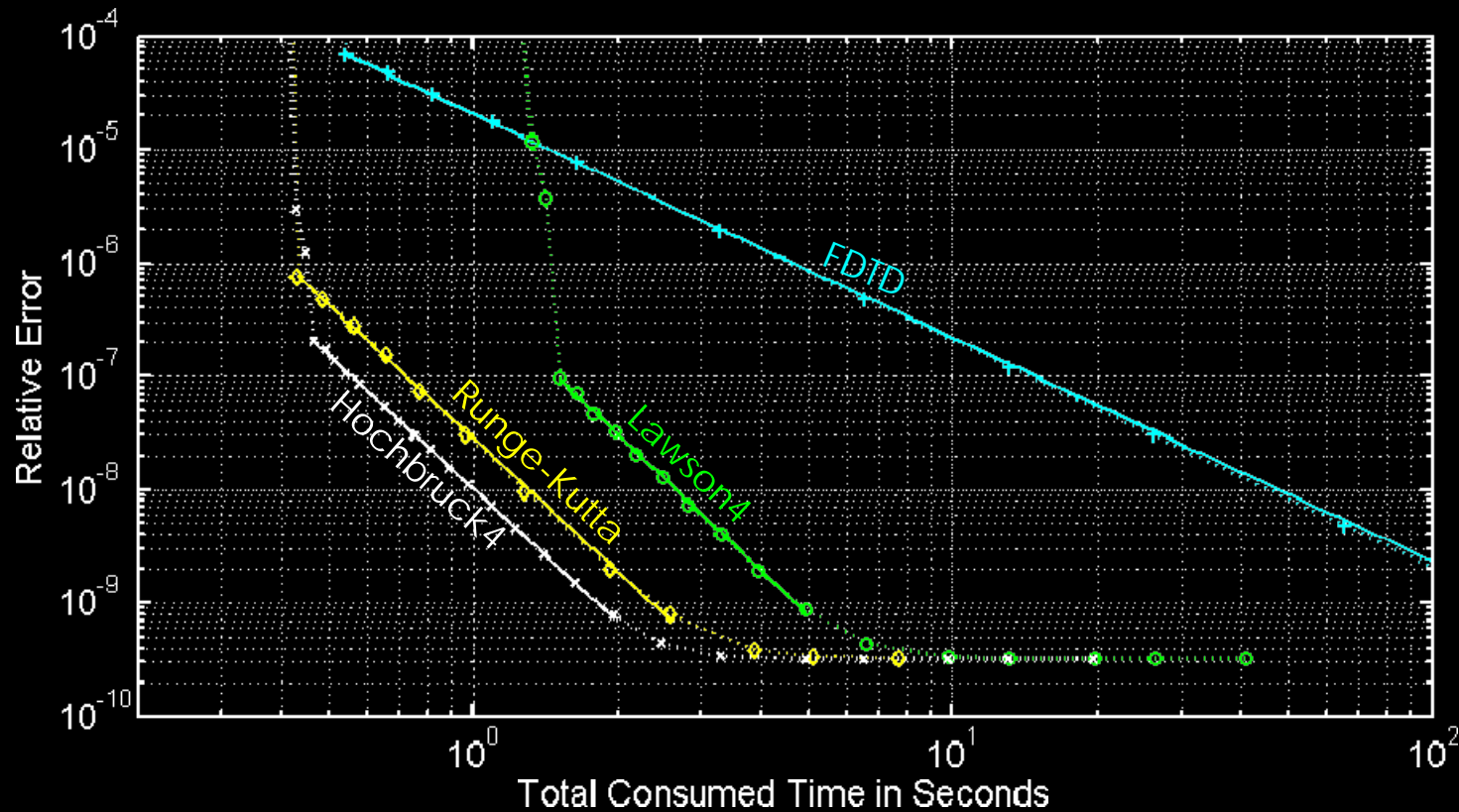
- With a standard Euler scheme, one obtains the “Lawson-Euler Scheme”:

$$\Psi(t + \Delta t) = e^{\Delta t H} \Psi(t) + \Delta t e^{\Delta t H} N[\Psi(t)]$$

- In practice, we use a 4th-order Runge-Kutta scheme instead of Euler: “Lawson4”
- Rosenbruck-Wanner solver proposed by Hochbruck and Lubich: “Hochbruck4”

Performance Comparison

- Dispersion-free 1D system with Kerr-Nonlinearity



M. Pototschnig et al., submitted (2007)

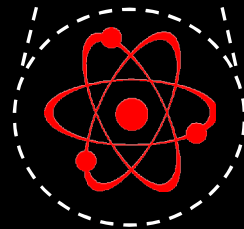
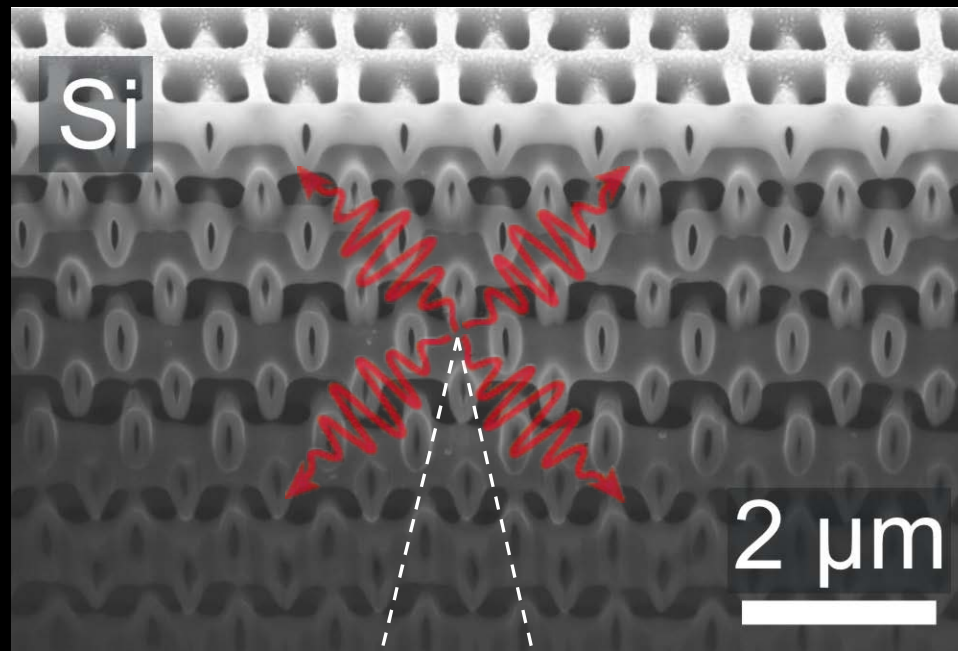


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Modified Radiation Dynamics



Semi-classical Description

- Full Hamiltonian: $\mathcal{H} = \mathcal{H}_{Atom} + \mathcal{H}_{Field} + \mathcal{H}_{Int}$

$$\mathcal{H}_{Atom} = E_0 |0\rangle \langle 0| + E_1 |1\rangle \langle 1|$$

$$\mathcal{H}_{Int} = -e\mathbf{r}\mathbf{E}$$

- Field is treated classically via Maxwell's Equations with polarization

$$\mathbf{P} = -n_{Atom}e \langle \mathbf{r} \rangle$$



Semi-classical Description

- Introducing the density matrix ρ which obeys

$$i\hbar \frac{\partial \rho}{\partial t} = [H, \rho]$$

$$\rho_1 = 2\text{Re}(\rho_{12}), \quad \rho_2 = 2\text{Im}(\rho_{21}), \quad \rho_3 = \rho_{22} - \rho_{11}$$

$$\frac{\partial}{\partial t} \begin{pmatrix} \rho_1 \\ \rho_2 \\ \rho_3 \end{pmatrix} = \begin{pmatrix} 0 & \omega_0 & 0 \\ -\omega_0 & 0 & 2\Omega_R \\ 0 & -2\Omega_R & 0 \end{pmatrix} \begin{pmatrix} \rho_1 \\ \rho_2 \\ \rho_3 \end{pmatrix} - \begin{pmatrix} \frac{1}{T_2} & 0 & 0 \\ 0 & \frac{1}{T_2} & 0 \\ 0 & 0 & \frac{1}{T_1} \end{pmatrix} \begin{pmatrix} \rho_1 \\ \rho_2 \\ \rho_3 - \rho_{30} \end{pmatrix}$$

$$\Omega_R = \frac{\gamma}{\hbar} E$$

T_1 : Relaxation

T_2 : Dephasing

γ : Dipole moment

Initial population difference



Semi-classical Description

Maxwell-Boch-Equations in 1D

$$\frac{\partial H}{\partial t} = -\frac{1}{\mu} \frac{\partial E}{\partial x}$$

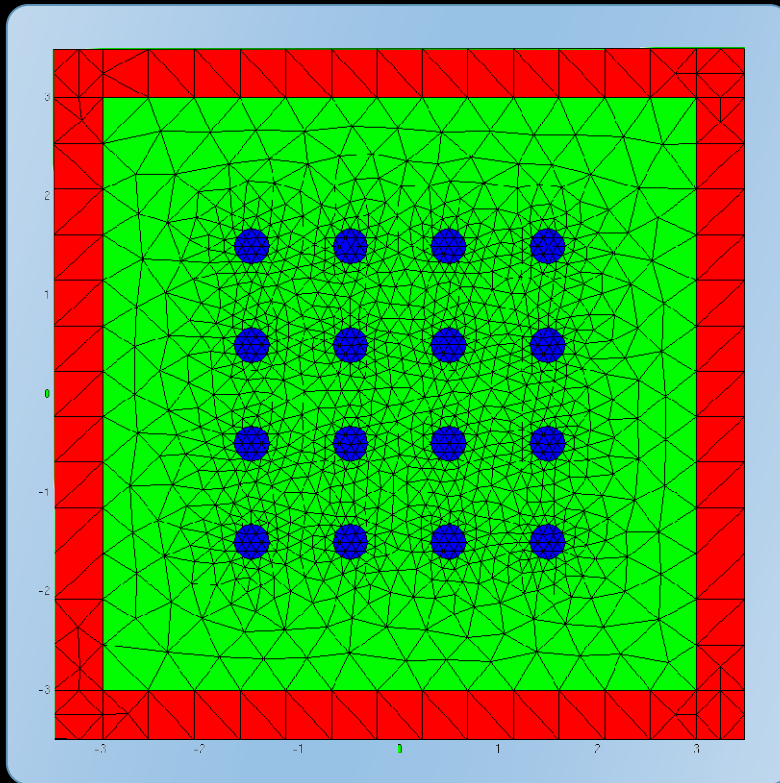
$$\frac{\partial E}{\partial t} = -\frac{1}{\epsilon(x)} \frac{\partial H}{\partial x} - \frac{N\gamma}{\epsilon(x)T_2} \rho_1 + \frac{N\gamma\omega_0}{\epsilon(x)} \rho_2$$

$$\frac{\partial \rho_1}{\partial t} = -\frac{1}{T_2} \rho_1 + \omega_0 \rho_2$$

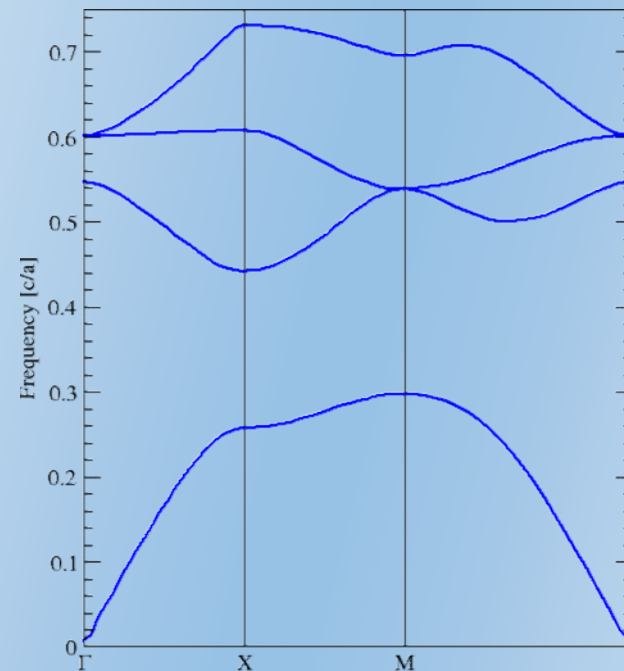
$$\frac{\partial \rho_2}{\partial t} = -\frac{1}{T_2} \rho_2 - \omega_0 \rho_1 + 2\frac{\gamma}{\hbar} E \rho_3$$

$$\frac{\partial \rho_3}{\partial t} = -2\frac{\gamma}{\hbar} E \rho_2 + \frac{1}{T_1} (\rho_3 - \rho_{30})$$

Spontaneous Emission in 2D PhCs



Corresponding bandstructure

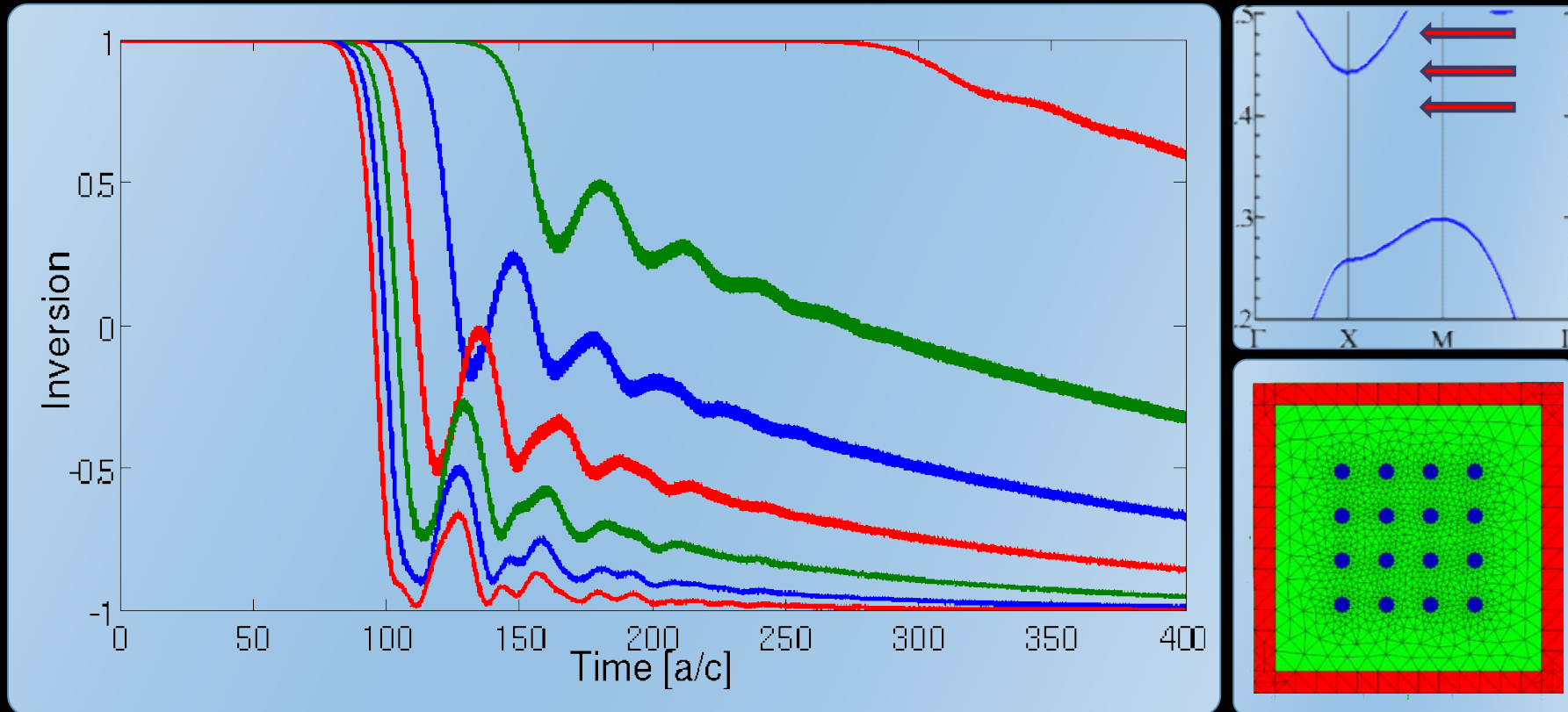


J. Niegemann et al., in preparation



Spontaneous Emission in 2D PhCs

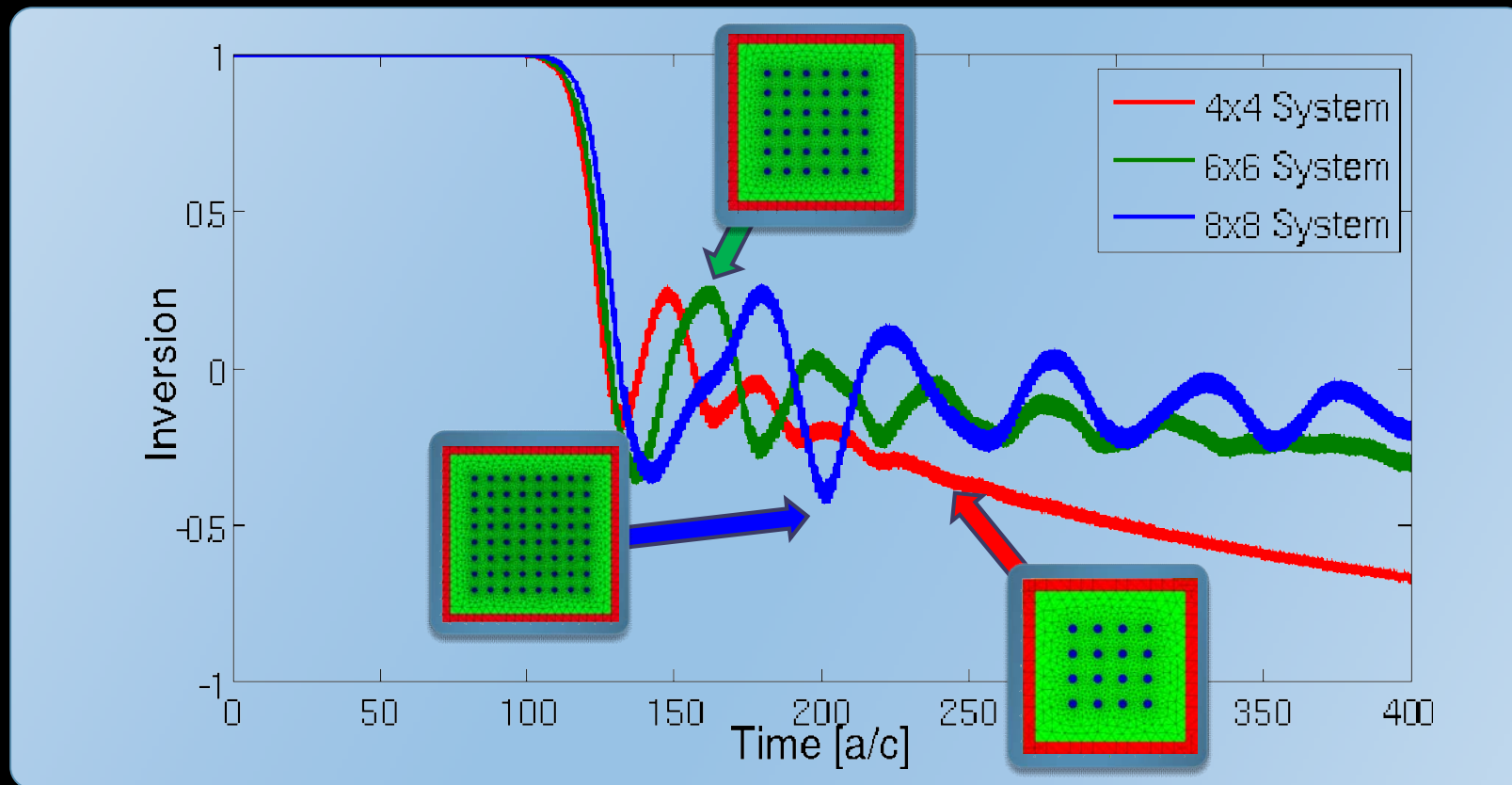
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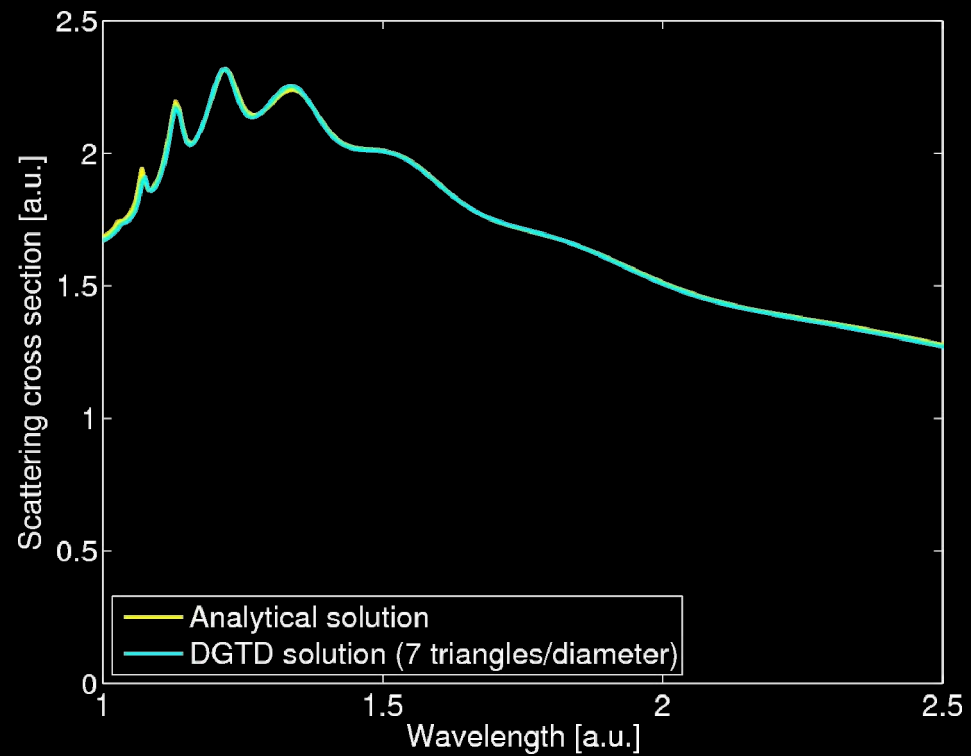
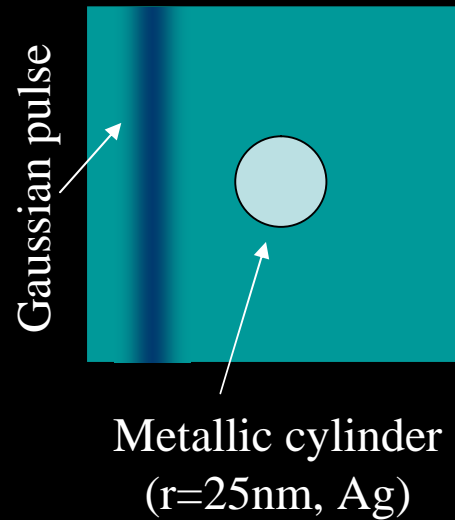
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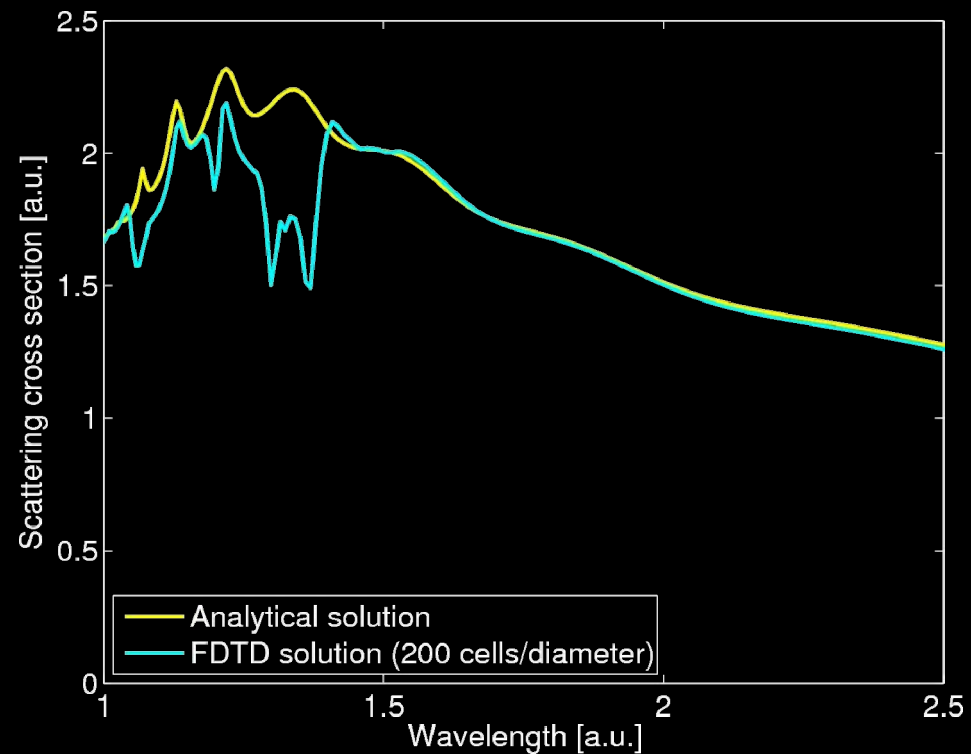
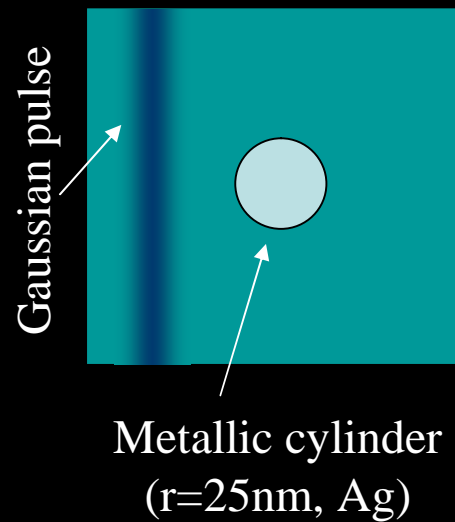
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Resonances of Plasmonic Structures

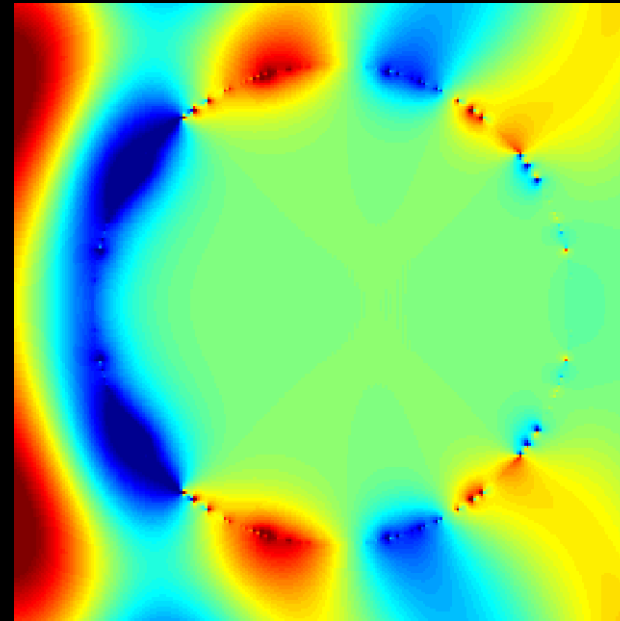
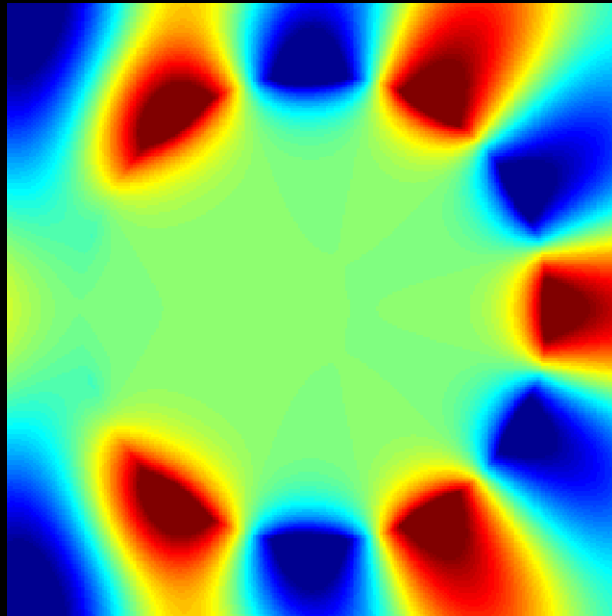


Resonances of Plasmonic Structures

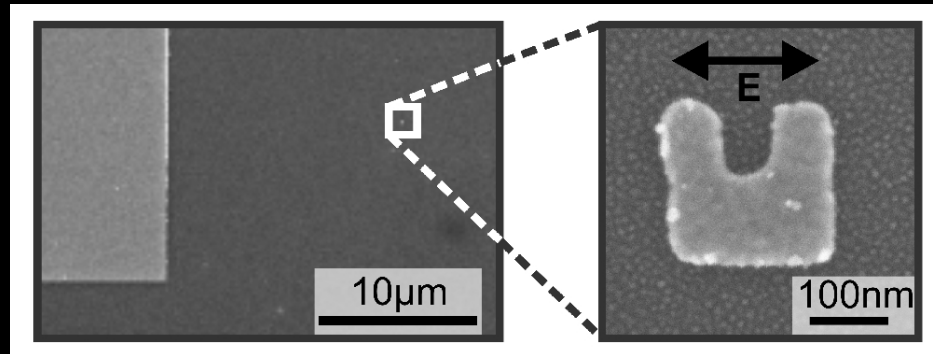


Resonances of Plasmonic Structures

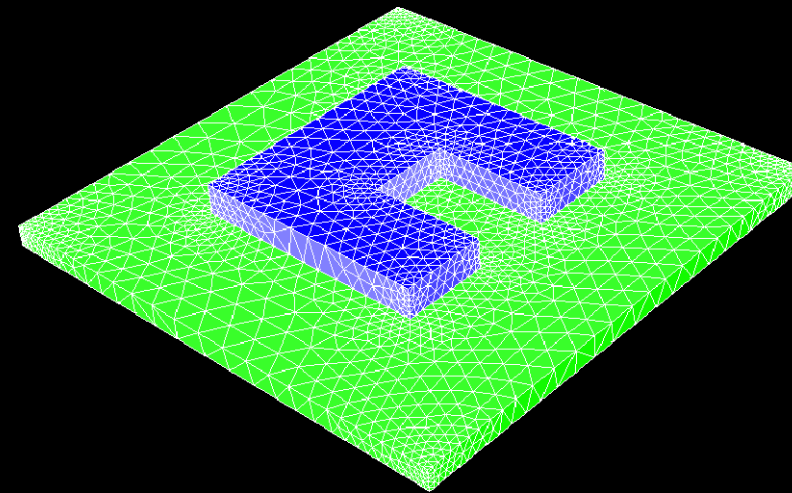
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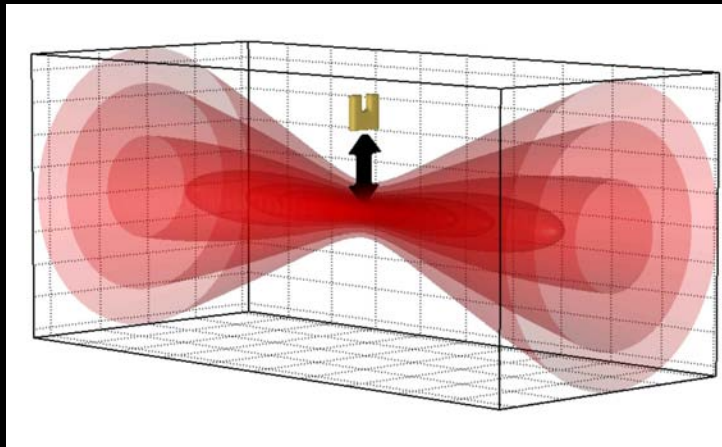
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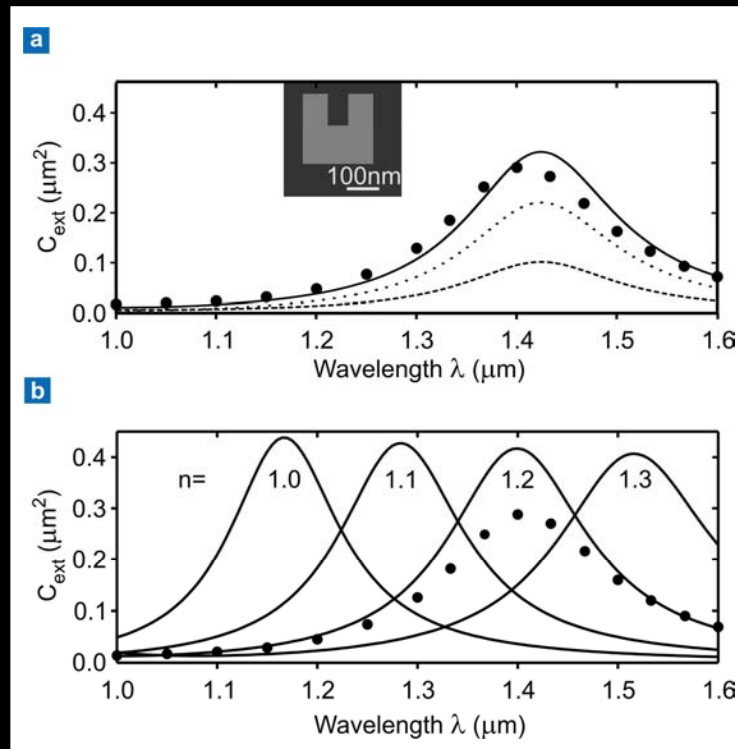
Courtesy of Martin Husnik



Resonances of Plasmonic Structures



M. Husnik et al., submitted



Summary and Outlook

- Higher-order time-domain simulation of the Maxwell equations using Krylov-subspace methods
- Sources, UPMLs/CPML and dispersive materials (Sellmeier-type) via auxiliary fields
- Discontinuous Galerkin technique for “conformal” spatial discretization
- Extension to nonlinear and coupled systems’ dynamics
- Future work:
 - Parallelization
 - **Application to complex photonic systems**

